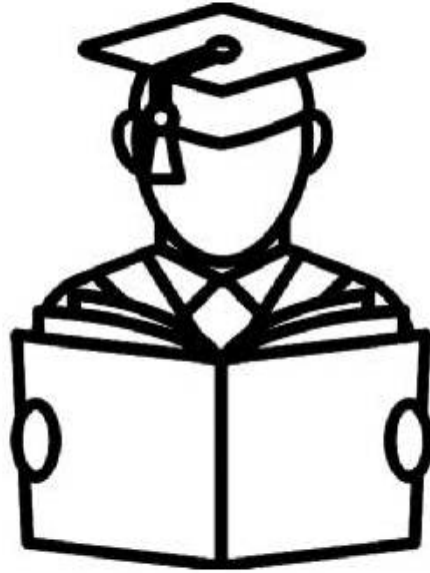


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"I don't love studying. I hate studying. I like learning. Learning is beautiful."



"An investment in knowledge pays the best interest."

Hi, My Name is

Mathematical Science
for CSIR NET
Academy of Mathematical
Education(AME)

Monu Kumar

Complex Analysis

Complex Number:-

A complex number is defined as the ordered pair (x, y) of real no., $z = (x, y)$ satisfying rules for addition and multiplication -

$$z_1 + z_2 = (x_1 + x_2, y_1 + y_2)$$

$$z_1 z_2 = (x_1 x_2 - y_1 y_2, x_1 y_2 + y_1 x_2)$$

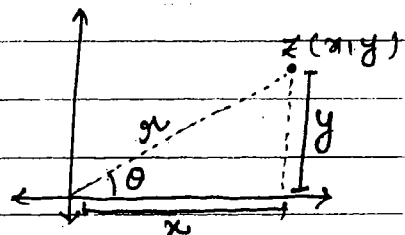
Every complex no. can be written as -

$$z = x + iy, \quad x, y \in \mathbb{R}$$

where $x = r \cos \theta$ and $y = r \sin \theta$

i.e. $x + iy = r(\cos \theta + i \sin \theta)$

or, $z = x + iy = r e^{i\theta}$



which is polar form of complex no.

and $r = \sqrt{x^2 + y^2}$, $\theta = \tan^{-1}\left(\frac{y}{x}\right)$

where, θ is argument of z i.e. the angle with the line joining the point with origin makes the +ve direction of x-axis.

NOTE:-

(i) $|z - z_0|$ = Distance of z from z_0

(ii) $|z|$ = Distance of z from origin

(iii) argument of z is not defined at origin

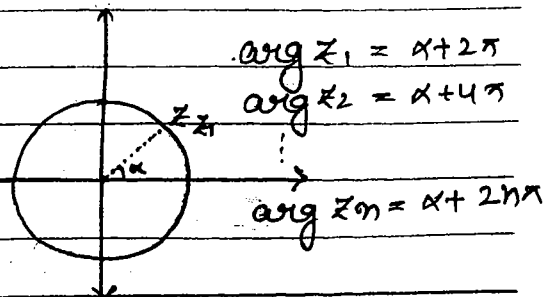
argument of z ($\arg z$) :-

any value of θ which satisfy

$$x = r \cos \theta \quad \text{and} \quad y = r \sin \theta$$

is called argument of z

and denoted as ' $\arg z$ '



we know, $z = e^{i\phi}$

$$\phi = \theta + 2m\pi$$

$$z = e^{i(\theta + 2m\pi)}$$

$$z = e^{i\theta} e^{i2m\pi}$$

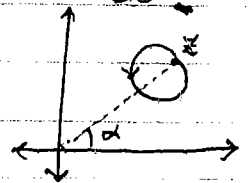
$$\boxed{z = e^{i\theta}} \quad [\because e^{i2m\pi} = \cos 2m\pi + i \sin 2m\pi]$$

$$\Rightarrow \arg z = \{ \theta + 2m\pi ; m \in \mathbb{Z} \}$$

NOTE :-

If origin is not enclosed after each revolution then argument of z will be unchanged.

i.e. $\arg z = \alpha$ for all revolutions



Argument of z ($\text{Arg} z$):-

For any $z \neq 0$, principal value of $\arg z$ is defined to be unique value that satisfies

$$\boxed{-\pi < \arg z \leq \pi}$$

And it is denoted by $\text{Arg} z$

$$\arg z = \{ \text{Arg} z + 2m\pi ; m \in \mathbb{Z} \}$$

where $-\pi < \text{Arg} z \leq \pi$

NOTE :-

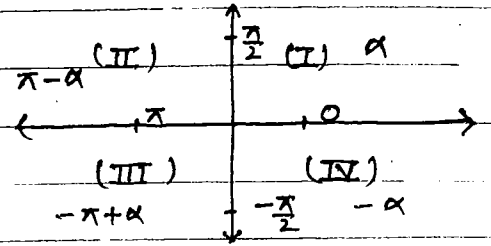
1. 2 complex no are equal iff their principle argument (i.e. $\text{Arg} z$) and modulus are same.

2. At origin (0,0) [i.e. $x=0$ & $y=0$] $\text{Arg} z$ is not defined.

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Principal argument of z (ie. $\text{Arg } z$)

let $\arg z = \tan^{-1} \left(\frac{y}{x} \right) + 2m\pi$



then,

$$\text{Arg } z = \begin{cases} 0 & , & x > 0, y = 0 \\ \alpha & , & x > 0, y > 0 \\ \pi/2 & , & x = 0, y > 0 \\ \pi - \alpha & , & x < 0, y > 0 \\ \pi & , & x < 0, y = 0 \\ \alpha - \pi & , & x < 0, y < 0 \\ -\pi/2 & , & x = 0, y < 0 \\ -\alpha & , & x > 0, y < 0 \end{cases}$$

where, $\alpha = \tan^{-1} \left| \frac{y}{x} \right|$

let $z = x + iy$, $x > 0, y > 0$

$\text{Arg } z = \tan^{-1} \left(\frac{y}{x} \right) \Rightarrow \text{Arg } z = \alpha$ and $0 < \text{Arg } z < \pi/2$

Q. Find the line of -

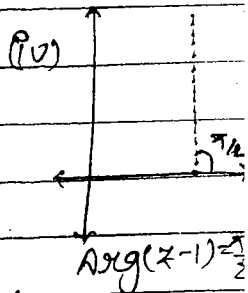
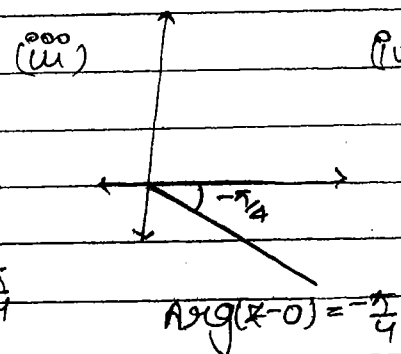
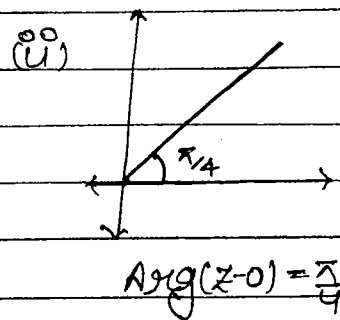
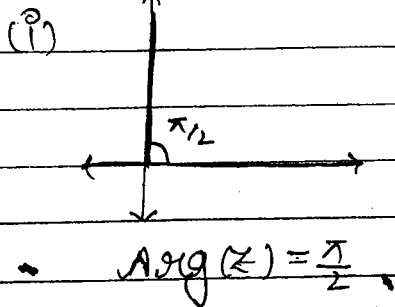
(i) $\text{Arg } z = \pi/2$

(ii) $\text{Arg } z = \pi/4$

(iii) $\text{Arg } z = -\pi/4$

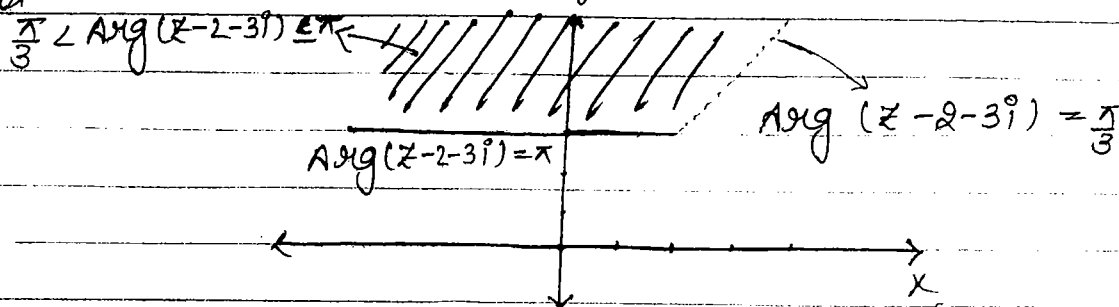
(iv) $\text{Arg}(z-1) = \pi/2$

soln



Q. Find the region of $\frac{\pi}{3} < \text{Arg}(z-2-3i) \leq \pi$

Soln



Q. Find $\arg z$, where

(i) $z = 1+i$

(ii) $z = i$

Soln (i) $z = 1+i$

$$\text{Arg } z = \alpha = \tan^{-1} \left| \frac{y}{x} \right| = \tan^{-1}(1) = \frac{\pi}{4}$$

$$\therefore \arg z = \left\{ \frac{\pi}{4} + 2n\pi; n \in \mathbb{Z} \right\}$$

(ii) $z = i$

$$\text{Arg } z = \alpha = \tan^{-1} \left| \frac{y}{x} \right| = \tan^{-1}(\infty) = \frac{\pi}{2}$$

$$\therefore \arg z = \left\{ \frac{\pi}{2} + 2n\pi; n \in \mathbb{Z} \right\}$$

Result:-

If z_1 and z_2 are two non-zero complex no. then

1. $\arg(z_1 z_2) = \arg z_1 + \arg z_2$

pf:- $z_1 = r_1 e^{i\theta_1} \Rightarrow \arg(z_1) = \theta_1 + 2m\pi$

$z_2 = r_2 e^{i\theta_2} \Rightarrow \arg z_2 = \theta_2 + 2n\pi$

$z_1 z_2 = r_1 r_2 e^{i(\theta_1 + \theta_2)}$

$\Rightarrow \arg(z_1 z_2) = \left\{ \theta_1 + \theta_2 + 2m\pi; m \in \mathbb{Z} \right\}$

$= \left\{ \theta_1 + 2m_1\pi; m_1 \in \mathbb{Z} \right\} + \left\{ \theta_2 + 2(m_2 - m_1)\pi; m_2 \in \mathbb{Z} \right\}$

$= \arg z_1 + \arg z_2$

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$$2. \arg \left(\frac{z_1}{z_2} \right) = \arg z_1 - \arg z_2$$

$$3. \arg z^m \neq m \arg z, \text{ but } \arg z^m = \underbrace{\arg z + \dots + \arg z}_{(m\text{-times})}$$

$$4. \operatorname{Arg}(z_1 \cdot z_2) \neq \operatorname{Arg} z_1 + \operatorname{Arg} z_2$$

Ex :- $z_1 = 2i$ and $z_2 = -5$

$$\operatorname{Arg} z_1 = \pi/2, \quad \operatorname{Arg} z_2 = \pi$$

$$z_1 \cdot z_2 = -10i$$

$$\Rightarrow \operatorname{Arg}(z_1 \cdot z_2) = -\pi/2 \neq \pi + \pi/2$$

$$5. \operatorname{Arg}(z_1 \cdot z_2) = \operatorname{Arg} z_1 + \operatorname{Arg}(z_2)$$

iff $-\pi < \operatorname{Arg}(z_1 + z_2) \leq \pi$

$$6. \operatorname{Arg}(z_1/z_2) \neq \operatorname{Arg} z_1 - \operatorname{Arg} z_2$$

$$7. \operatorname{Arg}(z_1/z_2) = \operatorname{Arg} z_1 - \operatorname{Arg} z_2, \text{ iff } -\pi < \operatorname{Arg}(z_1 - z_2) \leq \pi$$

Positional Equal Number :-

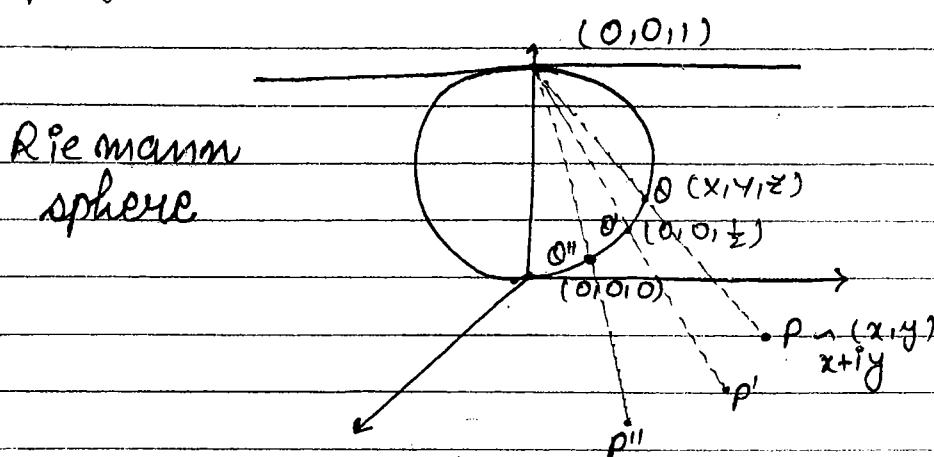
Complex no. z_1, z_2 are said to be positional equal no. if

(i) $|z_1| = |z_2|$ and

(ii) $\arg z_1 - \arg z_2 = 2m\pi, m \in \mathbb{Z}$

Stereographic Projection :-

We consider the extended complex plane $\mathbb{C} \cup \{\infty\}$ as a closed surface having a single point at infinity. We shall then introduce a new metric to describe the behavior of a complex function at infinity and to map the points in \mathbb{C} into the surface of a sphere. This process will be referred as stereographic projection.



A one-to-one correspondence b/w the sphere $(x-0)^2 + (y-0)^2 + (z-1/2)^2 = 1/4$ - (1) and the extended complex plane $\mathbb{C}_\infty = \mathbb{C} \cup \{\infty\}$ is called stereographic projection.

Equation of sphere and eqⁿ of line passes through (0,0,1) and (x,y,0)

$$\frac{x-0}{x-0} = \frac{y-0}{y-0} = \frac{z-1}{0-1} = \mu \quad (2)$$

$$x = \mu x, \quad y = \mu y, \quad z = -\mu + 1$$

from (2), $(\mu x)^2 + (\mu y)^2 + (-\mu + 1 - 1/2)^2 = 1/4$

$$\mu^2 (x^2 + y^2 + 1) = \mu$$

$$\mu = \frac{1}{x^2 + y^2 + 1}$$

* Vector Space *

D. 16/03/18

Defn - Let 'V' be a Nonempty set and $(F, +, \cdot)$ be a field.
Now, define an external composition, $f: F \times V \rightarrow V$
s.t. $f(\alpha, x) = \alpha \cdot x$ then, structure $(V, +, \cdot)$
is said to be a vector space and written as, $V(F)$
under the following conditions,

1) $(V, +)$ is abelian group.

(i) $a + b \in V \quad \forall a, b \in V$ — (closure property)

(ii) $a + (b + c) = (a + b) + c, \quad \forall a, b, c \in V$ — (Associative property)

(iii) $\forall a \in V \exists -a \in V$ s.t. $a + (-a) = (-a) + a = 0$
— (Inverse)

(iv) $0 \in V$ s.t. $a + 0 = a = 0 + a \quad \forall a \in V$ — (identity)

(v) $a + b = b + a, \quad \forall a, b \in V$ — (commutative property)

2) $\forall \alpha \in F \quad \forall x, y \in V.$

$$\text{s.t. } \alpha \cdot (x + y) = \alpha \cdot x + \alpha \cdot y$$

3) $\forall \alpha, \beta \in F \quad \forall x \in V.$

$$\text{s.t. } (\alpha + \beta) \cdot x = \alpha \cdot x + \beta \cdot x$$

4) $\forall \alpha, \beta \in F \quad \forall x \in V$

$$\text{s.t. } (\alpha \cdot \beta) \cdot x = \alpha \cdot (\beta \cdot x)$$

5) If 1 - unity of field

$$1 \cdot x = x, \quad \forall x \in V.$$

- Note - ① members of $(V, +, \cdot)$ or 'v' is called vector.
 ② vector addition and scalar multiplication are only allowed.
 ③ vector multiplication is not allowed.

ex. ① $V(F) = \mathbb{R}(\mathbb{R})$
 if, $x = 2 \in V = \mathbb{R}$
 $y = 3 \in V = \mathbb{R}$
 but, $x \cdot y$ is not allowed.

$\Rightarrow \cdot$ is not a Binary operation over domain (function) from $V \times V \rightarrow V$.

④ $(V, +, \cdot)$ is not an algebraic structure.

ex. ①. $V = \emptyset, F = \mathbb{R}$
 $\Rightarrow V = (\emptyset, +, \cdot)$
 $F = (\mathbb{R}, +, \cdot)$
 \nexists any external composition, $f: F \times V \rightarrow V$
 i.e., $f: \mathbb{R} \times \emptyset \rightarrow \emptyset$

$f(x, x) = x \cdot x$

as $f(\sqrt{3}, 2) = \sqrt{3} \cdot 2 = 2\sqrt{3} \notin \emptyset$

$\Rightarrow (V, +, \cdot)$ is not vector space over field $(\mathbb{R}, +, \cdot)$

ex. ②. $V = \{(x, y) \mid x, y \geq 0\}, F = \mathbb{R}$.

$\Rightarrow \alpha \in F = \mathbb{R}$

$x = (x, y) \in V$

① $\alpha \cdot x = (\alpha x, \alpha y) \in V$, when, $(\alpha \cdot x) \cdot (\alpha \cdot y) = \alpha^2 \cdot x \cdot y \geq 0$

(ii) $(V, +)$ is abelian group.

$$x = (-3, -5) \Rightarrow (-3) \cdot (-5) = 15 \in V \quad (\because 15 > 0)$$

$$\Rightarrow x = (-3, -5) \in V.$$

$$y = (2, 6) \Rightarrow 2 \cdot 6 = 12 \in V \Rightarrow y \in V.$$

$$x + y = (-1, 1) = (-1) \cdot 1 = -1 \notin V \Rightarrow x + y \notin V.$$

\Rightarrow closure not satisfied \Rightarrow Not abelian

$\Rightarrow (V, +, \cdot)$ is not vector space.

ex. 3

$V = (\mathbb{Z}_{10}, +_{10}, \times_{10}) \longrightarrow$ is ring not I.P.

$$F = \{0, 2, 4, 6, 8, +_{10}, \times_{10}\}$$

F is commutative with unity with multiplication inverse.

\Rightarrow 'F' is field

$$\left. \begin{array}{l} 0 \times_{10} 6 = 0 \\ 2 \times_{10} 6 = 2 \\ 4 \times_{10} 6 = 4 \\ 6 \times_{10} 6 = 6 \\ 8 \times_{10} 6 = 8 \end{array} \right\} \Rightarrow 6 \text{ is unity of 'F'}$$

(i) $(V, +) = (\mathbb{Z}_{10}, +_{10})$ is abelian group.

$$\text{def, } x \in \mathbb{Z}_{10}$$

$$\alpha \cdot x_{10} \quad \alpha \in \mathbb{Z}_{10}$$

$$\alpha \cdot (x + y) = \alpha \cdot x + \alpha \cdot y$$

$$(\alpha + \beta) x = \alpha \cdot x + \beta \cdot x$$

$$\begin{array}{l} \cdot \rightarrow \times_{10} \\ + \rightarrow +_{10} \end{array}$$

$$(\alpha \cdot \beta) x = \alpha \cdot (\beta \cdot x)$$

Here, unity = 6, i.e. $1 = 6$

$$6 \times_{10} 5 = 0 \neq 5 \quad (5 \in \mathbb{Z}_{10})$$

i.e. $1 \cdot x \neq x$ for some $x \in \mathbb{Z}_{10}$

$\Rightarrow (V, +, \cdot)$ is not vector space over field F.

ex. 4.

$$V = \{(a_1, a_2^2, a_3), a_1, a_2, a_3 \in \mathbb{R}\}$$

if any $(x, y, z) \in \mathbb{R}^3$ want to be member of V , it should be written as,

$$(x, t^2, z), \text{ where, } t^2 = y, \text{ for some } t \in \mathbb{R}.$$

$$\text{let, ex. } (0, -1, 0) \in \mathbb{R}^3 \nexists t \in \mathbb{R} \text{ s.t. } (0, -1, 0) = (0, t^2, 0)$$

$$\Rightarrow (0, -1, 0) \notin V.$$

$$x = (1, 1, 1) \in V \text{ as } (1, 1, 1) = (1, (1)^2, 1)$$

$$-x = (-1, -1, -1) \notin V \leftarrow \text{(additive inverse element not exist)}$$

$\Rightarrow V$ is not vector space.

ex. 5.

$$V = \{(a_1, a_2^3, a_3), a_i \in \mathbb{R}\}, F = (\mathbb{R}, +, \cdot)$$

vector addition - $x = (x_1, y_1, z_1) \in V$

$$y = (x_2, y_2, z_2) \in V$$

$$\text{b'coz, } x = (x_1, t_1^3, z_1) \text{ for some } t_1 \in \mathbb{R}$$

$$y = (x_2, t_2^3, z_2), \text{ for some } t_2 \in \mathbb{R}$$

$$x+y = (\underbrace{x_1+x_2}_{x_1}, \underbrace{t_1^3+t_2^3}_{y_1}, \underbrace{z_1+z_2}_{z_1})$$

$$x_1 \in \mathbb{R}$$

$$y_1 \in \mathbb{R}$$

$$z_1 \in \mathbb{R}$$

$$t_1^3 + t_2^3 = y_1 \in \mathbb{R} \quad (\because \text{range of } x^3 = \mathbb{R})$$

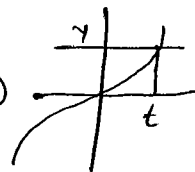
$$\exists t \in \mathbb{R} \text{ s.t. } y_1 = t^3$$

$$\text{then, } x+y = (x_1, t^3, z_1) \in V$$

$\Rightarrow V$ also can be written as,

$$V = \{(t_1, t_2^3, t_3), t_1, t_2, t_3 \in \mathbb{R}\}$$

$\Rightarrow \therefore V = \mathbb{R}^3 \Rightarrow V$ is vector space over $(\mathbb{R}, +, \cdot)$



ex. 6 . $V = \{ A = (a_{ij})_{2 \times 2}, a_{ij} \in \mathbb{R} \}$

$F = \left\{ \begin{bmatrix} a & a \\ a & a \end{bmatrix}, a \in \mathbb{R} \right\} \Rightarrow$ subring of matrices of order 2 with real entries

not C.R.U.

(not commute with un)

$$\Rightarrow \begin{bmatrix} a & a \\ a & a \end{bmatrix} \begin{bmatrix} e & e \\ e & e \end{bmatrix} = \begin{bmatrix} 2ae & 2ae \\ 2ae & 2ae \end{bmatrix} = \begin{bmatrix} a & a \\ a & a \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \text{ (unity)}$$

Here, $\alpha \cdot X = \begin{bmatrix} a & a \\ a & a \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \in V$.

But $1 \cdot X = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$

$$= \begin{bmatrix} \frac{a_{11} + a_{21}}{2} & \frac{a_{12} + a_{22}}{2} \\ \frac{a_{11} + a_{21}}{2} & \frac{a_{12} + a_{22}}{2} \end{bmatrix}$$

$$\neq \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \notin V$$

\Rightarrow 'V' is not vector space over field \mathbb{F}

ALL MATERIAL AVAILABLE HERE

Hand Written Class Notes

JAM, GATE, NET for CSIR

MATHS, CHY, PHY, LIFE SCI .

NET for UGC

**ENG , ECO , HIS , GEO , PSCY , COM
ENV,.... Etc.**

GATE , IES , PSUs for ENGG.

ME, EC, EE, CS, CE .

IAS , JEE , NEET(PMT).



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* Examples of the vector space -

① n-tuple spaces -

(A) $V = \mathbb{R}^n = \{ (a_1, a_2, a_3, \dots, a_n), a_i \in \mathbb{R} \}, F = (\mathbb{R}, +, \cdot)$

under usual addition and scalar multiplication.

$$x + y = (a_1, a_2, \dots, a_n) + (b_1, b_2, \dots, b_n)$$

$$= (a_1 + b_1, a_2 + b_2, \dots, a_n + b_n)$$

$$\alpha \cdot x = \alpha (a_1, a_2, \dots, a_n) = (\alpha a_1, \alpha a_2, \dots, \alpha a_n)$$

$V(F) = \mathbb{R}^n(\mathbb{R})$ is always a vector space over field

$$\mathbb{R} \quad \forall n \geq 1.$$

(B) $V = \mathbb{F}^n = \{ (c_1, c_2, \dots, c_n), c_i \in \mathbb{F} \}, F = (\mathbb{F}, +, \cdot)$

$\mathbb{F}^n(\mathbb{F})$ is always a vector space over field \mathbb{F}

and over same operation's that defined in above.

$$x + y = (c_1, c_2, \dots, c_n) + (d_1, d_2, \dots, d_n) = (c_1 + d_1, c_2 + d_2, \dots, c_n + d_n)$$

$$\alpha \cdot x = \alpha \cdot (c_1, c_2, \dots, c_n) = (\alpha \cdot c_1, \alpha \cdot c_2, \dots, \alpha \cdot c_n)$$

If field is \mathbb{R} (general form of vectors with elements of field)

$$\alpha \cdot (a_1 + ib_1, a_2 + ib_2, a_3 + ib_3, \dots, a_n + ib_n) = (\alpha a_1 + \alpha ib_1, \alpha a_2 + \alpha ib_2, \dots, \alpha a_n + \alpha ib_n)$$

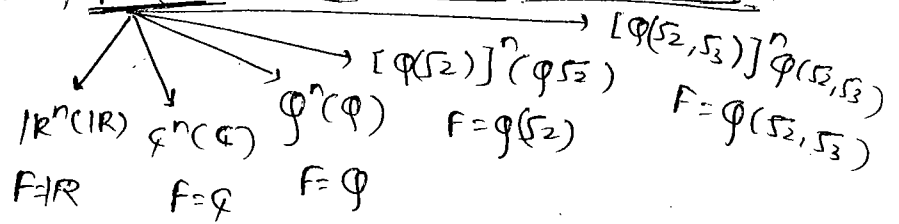
* $\mathbb{F}^2 = \{ (c_1, c_2) \}, F = \mathbb{R} \text{ i.e. } \mathbb{F}^2(\mathbb{R})$

$$\mathbb{F}^2 = \{ (a_1 + ib_1, a_2 + ib_2) \}$$

$$(1, 0) \quad (i, 0)$$

$$(0, 1), (0, i)$$

(c) If F is field, then, $F^n(F)$ is always a vector space.



(2) vector space of Matrices -

(A) $V = \{ (a_{ij})_{m \times n}, a_{ij} \in \mathbb{R} \}$, $F = (\mathbb{R}, +, \cdot)$
 $V(F)$ is a vector space of matrices of order m by n
 with real entries over field \mathbb{R} and also denoted as,

$M_{mn}(\mathbb{R})$ under the following operations,
 Usual Addition of matrices, and scalar multiplication.

$$X + Y = (a_{ij})_{m \times n} + (b_{ij})_{m \times n} = (a_{ij} + b_{ij})_{m \times n} = (c_{ij})_{m \times n}$$

$$\alpha \cdot X = \alpha \cdot (a_{ij})_{m \times n} = (\alpha \cdot a_{ij})_{m \times n} = (b_{ij})_{m \times n}$$

$\Rightarrow V(F)$ is vector space.

(B) $V = \{ A = (a_{ij})_{m \times n}, a_{ij} \in \mathbb{C} \}$, $F = (\mathbb{R}, +, \cdot)$

$$X + Y = (a_{ij})_{m \times n} + (b_{ij})_{m \times n} = (c_{ij})_{m \times n}$$

$$\alpha \cdot X = \alpha \cdot (a_{ij})_{m \times n} = \alpha (z_{ij} + i s_{ij}), z_{ij} + s_{ij} \in \mathbb{R}$$

$$= (\alpha \cdot z_{ij} + i \alpha s_{ij})$$

$\Rightarrow V(F)$ is a vector space over field \mathbb{R} .

③ Vector space of polynomials -

$$V = \{ p, p(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n, a_i \in \mathbb{R} \}, F = \mathbb{C} \text{ or } \mathbb{R}$$

or
 $V = \{ p, p(x) \text{ is polynomial with degree } p(x) \leq n \}$
 = space of polynomials of degree at most (n) . (ex or zero poly)
 under the following operations,

$$\begin{aligned} x + y &= p(x) + q(x) = (a_0 + a_1x + \dots + a_nx^n) + (b_0 + b_1x + \dots + b_nx^n) \\ &= (a_0 + b_0) + (a_1 + b_1)x + \dots + (a_n + b_n)x^n \end{aligned}$$

$$\begin{aligned} \alpha \cdot x &= \alpha \cdot p(x) = \alpha \cdot (a_0 + a_1x + a_2x^2 + \dots + a_nx^n) \\ &= \alpha \cdot a_0 + \alpha a_1x + \alpha a_2x^2 + \dots + \alpha a_nx^n \end{aligned}$$

④ vector space of functions -

(A) $V = \{ f; f: \mathbb{R} \rightarrow \mathbb{R} \}, F = (\mathbb{R}, +, \cdot)$
 = set of real valued functions defined on \mathbb{R} .

$V(F)$ is a vector space of real valued functions defined on \mathbb{R} .

$$f(x) + g(x) = (f+g)(x)$$

$$\alpha \cdot f(x) = (\alpha \cdot f)(x)$$

(B) $V = \{ f; f: S \subseteq \mathbb{R} \rightarrow \mathbb{R} \}, F = (\mathbb{R}, +, \cdot)$ (S is any interval)

$\Rightarrow V(F)$ is always a vector space.

Ques.
 * set of all transfinite no. over field \mathbb{R} . is vector space.

$$\Rightarrow \alpha_0 + c = c. (\alpha_0 \text{ identity})$$

⑤ vector space of sequences - (Non-funvs)

$$V = \{ \langle a_n \rangle, a_n \in \mathbb{R}, n \geq 1 \}, F = (\mathbb{R}, +, \cdot)$$

$V(F)$ is a vector space of sequences of real numbers over field \mathbb{R} under the following operations,

$$\langle a_n \rangle + \langle b_n \rangle = \langle a_1, a_2, \dots, a_n \rangle + \langle b_1, b_2, \dots, b_n \rangle \\ = \langle a_1 + b_1, a_2 + b_2, \dots, a_n + b_n \rangle$$

$$\alpha \cdot \langle a_n \rangle = \alpha \langle a_1, a_2, \dots, a_n \rangle \\ = \langle \alpha a_1, \alpha a_2, \dots, \alpha a_n \rangle \\ = \langle \alpha \cdot a_n \rangle$$

Non-funvs-

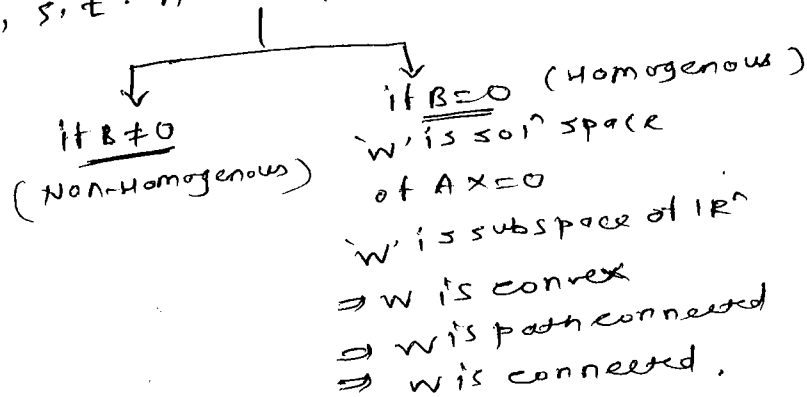
⑥ $V = \{ p, p(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n, n \in \mathbb{N}, a_i \in \mathbb{R} \}$
 $F = (\mathbb{R}, +, \cdot)$

$V(F) =$ space of polynomial over field \mathbb{R} .

or space of polynomial of all degree over \mathbb{R} .

sheet ①

①⑨ $W = \{ x \in \mathbb{R}^n, s.t. Ax = B \}$



$$W = \{x \in \mathbb{R}^n, \text{ s.t. } Ax = B\}$$

$B \neq 0$ (Non Homogenous)

$$x = 0 \in \mathbb{R}^n \text{ (n-tuple)}$$

but, $0 \notin W$.

$$A \cdot 0 \neq B$$

\Rightarrow W is not subspace

$B = 0$ (Homogenous)

W is solution space of $Ax = 0$.

- W is subspace of \mathbb{R}^n
- W is convex.
- W is path connected
- W is connected

No solution
No solution

$$W = \emptyset$$

can't discuss as a subspace,

- W is convex, (vacuously) (void situation)

- W is path connected
- W is connected
- W is bounded.

unique solⁿ

$$W = \{x\}$$

$$x \neq 0$$

- W is not subspace
- W is convex
- W is path connected
- W is connected
- W is bounded

infinite solution

W is an infinite

$$W = \{x \in \mathbb{R}^n, Ax = B\}$$

$$x, y \in W, Ax = B, Ay = B$$

$$A \cdot [\lambda \cdot x + (1-\lambda) \cdot y]$$

$$= A \lambda x + A (1-\lambda) y$$

$$= \lambda Ax + (1-\lambda) Ay$$

$$= B \lambda + (1-\lambda) B$$

$$= B \lambda + B - B \lambda$$

$$= B$$

- W is not subspace.
- W is convex
- W is connected
- W is path connected.

W is unbdd

* Discussion for 'W is unbdd in infinite solⁿ

Let, W be an infinite set of solⁿ of Homogenous system of Linear equation $Ax = 0$

$$W = \{x \in \mathbb{R}^n, \text{ s.t. } Ax = 0\}$$

$$x, y \in W, \alpha, \beta \in \mathbb{R}$$

$$\alpha \cdot x + \beta \cdot y = z \in \mathbb{R}^n$$

$$Az = A[\alpha \cdot x + \beta \cdot y] = \alpha \cdot A \cdot x + \beta \cdot A \cdot y$$

$$= \alpha \cdot 0 + \beta \cdot 0$$

'W' is subspace of \mathbb{R}^n .

Given, W is an infinite set.

$$\Rightarrow \exists w = (w_1, w_2, \dots, w_n) \in W,$$

st $w \neq 0 \Rightarrow$ atleast one $w_i \neq 0$.

say, w_j ($1 \leq j \leq n$)

$$\text{Now, } \|w\| = \|w\| = \sqrt{w_1^2 + w_2^2 + \dots + w_n^2}$$

\therefore W is a subspace.

$$\alpha, w \in W$$

$$\|\alpha \cdot w\| = |\alpha| \|w\|$$

As we increase α in \mathbb{R} , $\|\alpha \cdot w\|$ increases.

if α larger ($\alpha \rightarrow \infty$)

$$\|\alpha \cdot w\| \rightarrow \infty, \nexists M \text{ st. } \|x\| \leq M \forall x \in W.$$

\Rightarrow 'W' is unbdd.

* Subspace

Let 'W' be a non-empty subset of a vector space 'V' over field 'F'. Then this 'W' is said to be a subspace of vector space 'V', if 'W' is itself a vector space over same field 'F'. denoted as $W \leq V(F)$

ex ① $W = \{(a, b) \in \mathbb{R}^2, \underline{a, b \geq 0}\} \subseteq \mathbb{R}^2, W \neq \emptyset, \mathbb{R}^2(\mathbb{R})$ is a vector space.

$$W \neq \emptyset \subseteq \mathbb{R}^2$$

$$\text{at } x = (1, 2) \in W$$

$$\text{but, } -x = (-1, -2) \notin W.$$

$$\text{for, } x \in W \nexists -x$$

$$\text{st. } x + (-x) = 0$$

(W, +, \cdot) is not a group.

\Rightarrow (W, +, \cdot) is not a vector space. (By defⁿ)

* Test - Let, $W \neq \emptyset$ subset of $V(F)$,
 W is said to be a ~~vector~~ subspace,
iff,

(I) $x-y \in W \quad \forall x, y \in W.$

(II) $\alpha \cdot x \in W, \quad \forall \alpha \in F, x \in W$

\Rightarrow proof - 'W' is a subspace of V

we have,

$x-y \in W, \quad \forall x, y \in W \rightarrow$ (1)

$\& \alpha \cdot x \in W, \quad \forall \alpha \in F, x \in W \rightarrow$ (2)

by (1), $x=y$.

$\Rightarrow x-y \in W.$

i.e. $x-x = \boxed{0 \in W}$ - identity Axiom

Let $y \in W$ (arbitrary)

put $x=0$

$x-y = 0-y = \boxed{-y \in W}$ - inverse Axiom.

We know, $\forall y \in W, -y \in W$

put $x=x$.

$y=-y$

$x-y = x-(-y) = \boxed{x+y \in W}$ - Closure Axiom.

Associative Axiom (depends only on operation and here operation is not changed \Rightarrow satisfy.)

Commutative Axiom (also depends only on operation \Rightarrow it also satisfy)

$\Rightarrow (W, +)$ is abelian.

(given)

$\Rightarrow \alpha \cdot x \in W, \quad \forall \alpha \in F, x \in W.$ (external composition done)

$\therefore \alpha \cdot (x+y) = \alpha \cdot x + \alpha \cdot y \quad \forall \alpha, \beta \in F, \quad \forall x, y \in W.$

$\Rightarrow \alpha \cdot (x+y) = \alpha \cdot x + \alpha \cdot y, \quad \forall \alpha, \beta \in F, \quad \forall x, y \in W.$

depends only on operations.

$$\text{III) } (\alpha + \beta)x = \alpha \cdot x + \beta \cdot x, \quad \forall \alpha, \beta \in F, \quad \forall x, y \in W.$$

depends only on operations.

$$\text{IV) } (\alpha \cdot \beta) \cdot x = \alpha \cdot (\beta \cdot x), \quad \forall \alpha, \beta \in F, \quad \forall x, y \in W.$$

depends only on operations.

$$\text{V) } 1 \cdot x = x \quad \forall x \in W$$

Now, $(W, +, \cdot)$ is a vector space.

Combining these two conditions,

i.e. ① $x - y \in W, \quad \forall x, y \in W$

② $\alpha \cdot x \in W, \quad \alpha \in F, \quad \forall x \in W.$

we have a one step test,

$W \neq \emptyset \subseteq V(F)$ is said to be a subspace of $V(F)$

$$\text{iff } \boxed{\alpha \cdot x + \beta \cdot y \in W \quad \forall x, y \in W, \quad \forall \alpha, \beta \in F.}$$

Let 'A' be a square matrix with trace(A) = 2 ^{→ Nat Imp.}
 Now, which of the following are subspace of space of matrices over field IR.

✓ a) $W_1 = \{ x \in M_n(\mathbb{R}) = M_{nn}(\mathbb{R}), \text{ s.t. } A \cdot x = x \cdot A \}$

✓ b) $W_2 = \{ x \in M_n(\mathbb{R}) \text{ s.t. } x + A = A + x \}$

✓ c) $W_3 = \{ x \in M_n(\mathbb{R}) \text{ s.t. } \text{Tr}(Ax) = 0 \}$

⊘ d) $W_4 = \{ x \in M_n(\mathbb{R}) \text{ s.t. } |Ax| = 0 \}$
 ↳ det is not satisfying linear property.

Solⁿ

• Here 'A' is fixed matrix.

$x, y \in W_1$ (arbitrary)

$A \cdot x = x \cdot A$

$A \cdot y = y \cdot A$

$$\alpha \cdot x + \beta \cdot y = z \text{ (say)}$$

$$\begin{aligned} A \cdot z &= A \cdot (\alpha x + \beta y) \\ &= A \cdot \alpha x + A \cdot \beta y \\ &= \alpha Ax + \beta Ay \\ &= (\alpha x + \beta y) \cdot A \\ &= z \cdot A \end{aligned}$$

$$\Rightarrow AZ = ZA$$

$$\Rightarrow \alpha x + \beta y \in W_1$$

$$\Rightarrow W_1 \text{ is subspace}$$

Similarly W_2 is also subspace.

A space of n-tuple-

$$\# \underline{V = \mathbb{R}^n, F = \mathbb{R}}$$

$$\textcircled{1} W_1 = \{ (a_1, a_2, a_3, \dots, a_n) \in \mathbb{R}^n \text{ s.t. } \sum_{i=1}^n a_i = 0 \}$$

$$\textcircled{2} W_2 = \{ (a_1, a_2, a_3, \dots, a_n) \in \mathbb{R}^n \text{ s.t. } \sum_{i=1}^n (a_i)^2 = 0 \} \begin{matrix} \text{or} \\ \{0\} \\ \text{subspace} \end{matrix} = W_1 \cdot \{ (0, 0, \dots, 0) \}$$

$$\textcircled{3} W_3 = \{ (a_1, a_2, a_3, \dots, a_n) \in \mathbb{R}^{100}, a_1 = a_2 = \dots = a_{50} \text{ and } a_{51} + a_{52} + \dots + a_{100} = 0 \} \begin{matrix} \text{satisfy} \\ \text{linear} \\ \text{condition} \\ \text{= subspace} \end{matrix}$$

$$\textcircled{4} W_4 = \{ (a_1, a_2, a_3, \dots, a_{100}) \in \mathbb{R}^{100}, \text{ s.t. } a_1 = 2a_2 \}$$

$$\times \textcircled{5} W_5 = \{ (a_1, a_2, a_3, \dots, a_{10}) \in \mathbb{R}^{10} \text{ s.t. } \frac{a_1}{a_2} = 2 \}$$

$$\times \textcircled{6} W_6 = \{ (a_1, a_2, a_3) \in \mathbb{R}^3 \text{ s.t. } a_1 = a_2^2 \}$$

$$\textcircled{7} W_7 = \{ (a_1, a_2, a_3, \dots, a_n) \in \mathbb{R}^n, a_i = a_j = \left[\frac{n}{2} \right], i = \left[\frac{n-1}{2} \right] \}$$

$$\textcircled{8} W_8 = \{ (a_1^3, a_2^3, a_3^3, \dots, a_{10}) \in \mathbb{R}^{10}, a_4 + a_5 + \dots + a_{10} = 0 \}$$

$$\textcircled{9} W_9 = \{ (a_1, a_2, \dots, a_n) \in \mathbb{R}^n; \sum_{i=1}^n i a_i = 0 \} = \dim = n-1$$

$$\textcircled{10} W_{10} = \{ (a_1, a_2, \dots, a_n) \in \mathbb{R}^n; a_i = a_j \text{ when } i+j = \text{even} \}$$

Solⁿ (10) -
$$\left. \begin{aligned} x &= (a_1, a_2, \dots, a_n) \in W, & a_i &= a_j, & i+j &= \text{even}, \\ y &= (b_1, b_2, \dots, b_n) \in W, & b_i &= b_j, & i+j &= \text{even}, \end{aligned} \right\} \textcircled{1}$$

$$\alpha \cdot x + \beta \cdot y = (\alpha a_1 + \beta b_1, \alpha a_2 + \beta b_2, \dots, \alpha a_n + \beta b_n)$$

$$= (c_1, c_2, \dots, c_n)$$

$$\alpha a_i + \beta b_j = \alpha a_j + \beta b_j \quad \forall i+j = \text{even}$$

$$c_i = c_j, \quad \forall i+j = \text{even}$$

$$\Rightarrow (c_1, c_2, \dots, c_n) \in W.$$

$$\alpha \cdot x + \beta \cdot y \in W, \quad \forall \alpha, \beta \in F, \quad \forall x, y \in W.$$

$$\Rightarrow \underline{W_{10} \text{ is subspace.}}$$

Solⁿ (9) -
$$\begin{aligned} x &= (a_1, a_2, \dots, a_n) \in W, & \sum_{i=1}^n i a_i &= 0 \\ y &= (b_1, b_2, \dots, b_n) \in W, & \sum_{i=1}^n i b_i &= 0. \end{aligned}$$

$$\alpha \cdot x + \beta \cdot y = z = (c_1, c_2, \dots, c_n)$$

$$\text{then, } c_i = \alpha a_i + \beta b_i, \quad \forall i=1 \text{ to } n$$

$$\sum_{i=1}^n i c_i = \sum_{i=1}^n i (\alpha a_i + \beta b_i)$$

$$= \alpha \sum_{i=1}^n i a_i + \beta \sum_{i=1}^n i b_i$$

$$= \alpha \cdot 0 + \beta \cdot 0$$

$$= 0$$

$$\Rightarrow \alpha x + \beta y \in W.$$

$$\Rightarrow \underline{W_9 \text{ is subspace.}}$$

III

$$W = \{x \in \mathbb{R}^n, \text{ s.t. } Ax=0\}$$

 for fixed matrix A.

$$x \in W, Ax=0$$

$$y \in W, Ay=0.$$

$$\alpha \cdot x + \beta \cdot y \in W.$$

$$z = A(\alpha x + \beta y)$$

$$= \alpha Ax + \beta Ay$$

$$= \alpha \cdot 0 + \beta \cdot 0$$

$$= 0$$

$$\Rightarrow \alpha x + \beta y \in W$$

$$\Rightarrow \underline{W \text{ is subspace.}}$$

Soln 8 -

$$* W_{12} = \{ (x+y, x-y), x, y \in \mathbb{R}^n \}$$

$$\Rightarrow \alpha(x_1+y_1, x_1-y_1) + \beta(x_2+y_2, x_2-y_2)$$

$$= (\alpha x_1 + \alpha y_1 + \beta x_2 + \beta y_2, \alpha x_1 - \alpha y_1 + \beta x_2 - \beta y_2)$$

$$= (A_1 + A_2, A_1 - A_2, A_1, A_2 \in \mathbb{R}^n)$$

\Rightarrow W_{12} is a subspace.

Soln 9 - $W_8 = \{ (a_1^3, a_2^3, a_3^3, \dots, a_{10}^3) \in \mathbb{R}^{10}, a_1 + a_2 + \dots + a_{10} = 0 \}$

$$\Rightarrow x = (a_1^3, a_2^3, \dots, a_{10}^3) \in \mathbb{R}^{10}, \sum_{i=1}^{10} a_i = 0$$

$$y = (b_1^3, b_2^3, \dots, b_{10}^3) \in \mathbb{R}^{10}, \sum_{i=1}^{10} b_i = 0$$

$$\alpha \cdot x + \beta \cdot y = \left(\frac{\alpha a_1^3 + \beta b_1^3}{B_1}, \frac{\alpha a_2^3 + \beta b_2^3}{B_2}, \frac{\alpha a_3^3 + \beta b_3^3}{B_3}, \dots, \alpha a_{10}^3 + \beta b_{10}^3 \right)$$

$$= (B_1, B_2, B_3, A_4, \dots, A_{10})$$

$$= (B_1, B_2, B_3, A_4, \dots, A_{10})$$

$$\sum_{i=1}^{10} A_i = \sum_{i=1}^{10} (\alpha a_i + \beta b_i)$$

$$= \alpha \sum_{i=1}^{10} a_i + \beta \sum_{i=1}^{10} b_i$$

$$= 0 + 0$$

$$= 0$$

$$\Rightarrow \boxed{\sum_{i=1}^{10} A_i = 0}$$

There are B_1, B_2, B_3 are \rightarrow zero.

There are always A_1, A_2, A_3 s.t. $B_1 = A_1^3, B_2 = A_2^3, B_3 = A_3^3$

$$\Rightarrow B_i = A_i^3 \quad \forall i=1, 2, 3$$

$$\text{Here } \alpha x + \beta y = (A_1^3, A_2^3, A_3^3, A_4, A_5, \dots, A_{10})$$

\Rightarrow W_8 is subspace.

Solⁿ ⑦ $W_7 = \{ (a_1, a_2, \dots, a_n), a_i = a_{\lfloor \frac{n-1}{2} \rfloor}, \forall i = \lfloor \frac{n-1}{2} \rfloor \}$

\Rightarrow If $n=4$

$W = \{ (a_1, a_2, a_3, a_4) \in \mathbb{R}^4, a_i = a_2, \forall i=1,3,4 \}$

$\Rightarrow W = \{ (a_1, a_2, a_3, a_4) \in \mathbb{R}^4, a_1 = a_2, \forall i \}$ is subspace.

If $n=5$

$W = \{ (a_1, a_2, a_3, a_4, a_5) \in \mathbb{R}^5, a_i = a_2, i=2,3,4,5 \}$

$\Rightarrow W = \{ (a_1, a_2, a_3, a_4, a_5) \in \mathbb{R}^5, a_2 = a_2 \} = \mathbb{R}^5$

$\Rightarrow W_7$ is always form a subspace.

+ W_{13} = $\{ (a_1, a_2, a_3, \dots, a_n), a_i = a_{\lfloor \frac{n-1}{2} \rfloor}, \forall i=1,2,3, \dots, \lfloor \frac{n-1}{2} \rfloor \}$ — subspace.

Solⁿ ⑧ $W_6 = \{ (a_1, a_2, a_3) \in \mathbb{R}^3, a_1 = a_2^2 \}$
 \downarrow
 condition is not linear.

\Rightarrow Not subspace.

Solⁿ ⑨ - $W_5 = \{ (a_1, a_2, a_3, \dots, a_{10}) \in \mathbb{R}^{10} \text{ s.t. } \frac{a_1}{a_2} = 2 \}$

by default whatever condition given we need to check over that.

if also,
 $\Rightarrow (0, 0, 0, \dots, 0) \notin W_5$ as $\frac{0}{0}$ (not defined)

Solⁿ ⑩ $(0, 0, 0, \dots, 0) \in W_4 \Rightarrow$ subspace

① $W_{14} = \{ (a_1, a_2, a_3, \dots, a_n) \in \mathbb{R}^n, \text{ s.t. } a_1 + 2a_2 + a_3 = 0 \text{ and } a_2 + a_4 + a_5 = 0 \}$ is subspace

W_{14} can be written as,

$W_{14} = \{ X \in \mathbb{R}^5, AX=0, \text{ where } A = \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \end{bmatrix}_{2 \times 5}$
($n > m$)
(infini Sol)

* Space of Matrices -

$V = M_{mn}(\mathbb{R})$ - space of Matrices over field \mathbb{R} , of order $m \times n$.

$V = M_n(\mathbb{R})$ - space of Matrices of order ' n ' over field \mathbb{R}

① $W_{15} = \{ A \in M_n(\mathbb{R}), A \cdot A^T = 0 \} = \underline{W = \{0\}}$.

② $W_{16} = \{ A = (a_{ij})_{m \times n} \text{ s.t. } \sum_{j=1}^n a_{ij} = 0, \forall i=1 \text{ to } m \} = \underline{m \times (n-1)}$
sum of each row, is zero

③ $W_{17} = \{ A = (a_{ij})_{m \times n} \text{ s.t. } \sum_{i=1}^m a_{ij} = 0, \forall j=1 \text{ to } n \} = \underline{(m-1) \times n}$
sum of each column, is zero

④ $W_{18} = \{ A = (a_{ij})_{m \times n} \text{ s.t. } \sum_{j=1}^n a_{ij} = 0, \forall i=1 \text{ to } m \text{ \& } \sum_{i=1}^m a_{ij} = 0, \forall j=1 \text{ to } n \} = \underline{(m-1) \times (n-1)}$

⑤ $W_{19} = \{ A \in M_n(\mathbb{R}) \text{ s.t. } \text{trace}(A \cdot A^T) = 0 \} \Rightarrow W_{19} = \{0\}$
(contains only zero matrix)

⑥ $W_{20} = \{ A \in M_n(\mathbb{R}) \text{ s.t. } A^T = A \} = \underline{\Sigma_n}$

⑦ $W_{21} = \{ A \in M_n(\mathbb{R}) \text{ s.t. } A^T = -A \} = \underline{\frac{n(n-1)}{2}} = \underline{\Sigma_{n-1}}$

⑧ $W_{22} = \{ A \in M_n(\mathbb{R}) \text{ s.t. } \text{Trace}(A) = 0 \} = \underline{n^2 - 1}$

⑨ $W_{23} = \{ A = (a_{ij})_{n \times n}, \sum_{i=1}^n a_{ii} = 0, \& a_{ii} = 0 \} = \underline{n^2 - 2}$
trace $\neq 0$

⑩ $W_{24} = \{ A = (a_{ij})_{n \times n}, \sum_{i=1}^n a_{ii} = 0, a_{ii} = 0 \& a_{ij} = a_{ji}, \forall i \& j \} = \underline{\frac{(n-2)(n^2-1)}{2}}$
trace $\neq 0$ symmetric

SMP

✓ (11) $W_{25} = \{ A = (a_{ij})_{m \times n}, a_{ij} = 0, \text{ where } (i+j) = \text{even} \}$, $\dim = \frac{n^2}{2}$, n is even

(12) $W_{26} = \{ A = \begin{bmatrix} a_1 & a_2^3 \\ a_3^3 & a_4 \end{bmatrix}, a_i \in \mathbb{R}, \forall i=1 \text{ to } 4 \}$, $\frac{n^2}{2}$, n is odd

(13) $W_{27} = \{ A = (a_{ij})_{n \times n}, \text{ s.t. } a_{ij} = 0, \text{ whenever } (i+j) = n+1 \}$, $\dim W_{27} = \frac{n^2-n}{2}$

(14) $W_{28} = \{ A \in M_n(\mathbb{R}) \text{ s.t. } |A| = 0 \}$, $W = \{ A \in M_n(\mathbb{R}), \text{ s.t. } |A| \neq 0 \}$

(15) $W_{29} = \{ \text{Let } x \neq 0 \text{ vector in } \mathbb{R}^n, \text{ Now define, } W_{29} = \{ A \in M_n(\mathbb{R}), \text{ s.t. } Ax = x \}$

JMP
 (16) Let 'B' be a fixed matrix of order 'n' with real entries, Now, define a set,

$W_{30} = \{ A \in M_n(\mathbb{R}) \text{ s.t. } AB = BA \}$, = (nullspace)

(17) Let 'B' be a orthogonal matrix, Now define a set,

$W_{31} = \{ BAB^T; A \in M_n(\mathbb{R}) \}$

* with field \mathbb{F} -

$W_{32} = \{ A \in M_n(\mathbb{F}), A^0 = A \}$, (Here, $a_{ij} \in \mathbb{F} \neq \mathbb{F} = \mathbb{F}$) $\Rightarrow \dim W_{32} = n^2$ (not subspace)

$W_{33} = \{ A \in M_n(\mathbb{F}), A^0 = -A \}$, (-11) $\Rightarrow \dim W_{33} = 0$

$W_{34} = \{ A = (a_{ij})_{n \times n}, a_{ij} \in \mathbb{F}, A^0 = A \}$, $\mathbb{F} = \mathbb{R} \Rightarrow \dim W_{34} = \frac{n^2-n}{2} + n$

$= n^2 - n + n = n^2$

$W_{35} = \{ A = (a_{ij})_{n \times n}, a_{ij} \in \mathbb{F}, A^0 = -A \}$, $\mathbb{F} = \mathbb{R}$

$\dim W_{35} = \frac{n^2-n}{2}$

$W_{36} = \{$

* Note -

operation based matrices Not form a subspace, entries based matrices form a subspace,

* space of polynomials

* for vector space

- 1) if $\exists \alpha \in F$ or $x \in V$ s.t. $\alpha \cdot x \notin V$.
- 2) if $\exists x + y$ in V s.t. $x + y \notin V$.
- 3) if $0 \notin V$.
- 4) for some $x, \exists -x$ in V .
- 5) $\exists x$ in V s.t. $1 \cdot x \neq x$

If any one of the above is satisfied then V is not a vector space.

* for subspace

- 1) $0 \in W$.
- 2) if $\exists x, y \in W$ s.t. $x + y \notin W$.
- 3) if $\exists \alpha \in F$ or $x \in W$ s.t. $\alpha \cdot x \notin W$.

If any one of the above is satisfied then, W is not a subspace.

Solⁿ $W_{15} = \{A \in M_n(\mathbb{R}) : A \cdot A^T = 0\}$

$A = 0_{n \times n} \in W_{15}, 0 \cdot 0^T = 0$

$W_{15} \neq \emptyset$

$A, B \in W_{15} \Rightarrow A \cdot A^T = 0$
 $B \cdot B^T = 0$

$\alpha A + \beta B = C$

$C \cdot C^T = (\alpha A + \beta B) \cdot (\alpha A + \beta B)^T$
 $= (\alpha A + \beta B) \cdot (\alpha A^T + \beta B^T)$
 $= \alpha^2 A A^T + \alpha \beta A B^T + \beta \alpha B A^T + \beta^2 B B^T$
 $= 0 + \alpha \beta A B^T + \beta \alpha B A^T + 0$
 $= \alpha \beta (A B^T + B A^T)$

$A B^T = -B A^T$

generalised over 2x2 matrix,

If $A_{n \times n}$ s.t. $A \cdot A^T = 0$. then diagonal entry in i th row

$$= \sum_{j=1}^n (a_{ij})^2 = 0$$

$$\Rightarrow a_{ij} = 0, \forall i \neq j.$$

$$\Rightarrow A = 0. \text{ (zero matrix)}$$

Hence $W = \{0\}$.

$$\Rightarrow W_{15} \text{ is a subspace.}$$

Solⁿ

$$* W_{16} = \{ A = (a_{ij})_{m \times n}, \sum_{j=1}^n a_{ij} = 0, \forall i = 1 \text{ to } n \} \Rightarrow \boxed{\dim(W_{16}) = n \times (m-1)}$$

$$A = (0)_{m \times n} \in W_{16}, \text{ hence } W_{16} \neq \emptyset.$$

$$A = (a_{ij})_{m \times n} \in W_{16} \text{ as } \sum_{j=1}^n a_{ij} = 0, \forall i = 1 \text{ to } m$$

$$B = (b_{ij})_{m \times n} \in W_{16} \text{ as } \sum_{j=1}^n b_{ij} = 0, \forall i = 1 \text{ to } m.$$

$$\alpha \cdot A + \beta \cdot B = C \in W_{16}$$

$$\underline{\text{as}}, \alpha (a_{ij})_{m \times n} + \beta (b_{ij})_{m \times n} = (c_{ij})_{m \times n}$$

$$c_{ij} = \alpha a_{ij} + \beta b_{ij}.$$

$$\sum_{j=1}^n c_{ij} = \sum_{j=1}^n \alpha a_{ij} + \sum_{j=1}^n \beta b_{ij}$$

$$= \alpha \sum_{j=1}^n a_{ij} + \beta \sum_{j=1}^n b_{ij}$$

$$= 0 + 0$$

$$= 0$$

$$\Rightarrow W_{16} \text{ is a subspace.}$$

$$W_{16} = \{ A = (a_{ij})_{m \times n}, \sum_{j=1}^n a_{ij} = 0, \forall i = 1 \text{ to } m \}$$

for any 3×3 matrix.

$$\begin{bmatrix} a_{11} & a_{12} & -a_{11}-a_{12} \\ a_{21} & a_{22} & -a_{21}-a_{22} \\ a_{31} & a_{32} & -a_{31}-a_{32} \end{bmatrix}_{3 \times 3}$$

$$\Rightarrow \dim \text{ of } W_{16} \text{ for } m=3, n=3 = 6$$

$$\Rightarrow \dim(W_{16}) = \boxed{n \times (m-1)}$$

Similarly, W_{17} & W_{18} are also subspace.

$$\boxed{\dim W_{17} = (n-1) \times m} \quad \& \quad \dim W_{18} = \dots$$

$$* W_{10} = \{ A \in M_n(\mathbb{R}), \text{Tr}(A \cdot A^T) = 0 \}$$

$$a_{11}^2 + a_{22}^2 + a_{33}^2 + \dots + a_{nn}^2 = 0$$

$$\Rightarrow W_{10} = \{0\}$$

$$\Rightarrow W_{10} = \{0\}$$

$\Rightarrow W_{10}$ is subspace.

$$* W_{20} = \{ A \in M_n(\mathbb{R}), A^T = A \}$$

$0 \in W_{20}$, as $0 = 0^T$, $W_{20} \neq \emptyset$.

\Rightarrow let, $A \in W_{20}$ as $A^T = A$

$B \in W_{20}$ as $B^T = B$.

$$(\alpha A + \beta B)^T = (\alpha A)^T + (\beta B)^T$$

$$= \alpha A^T + \beta B^T$$

$$= \alpha A + \beta B$$

$$\Rightarrow \alpha A + \beta B \in W_{20}$$

\Rightarrow W_{20} is subspace

similarly, W_{21} is subspace, $\Rightarrow \boxed{\dim(W_{21}) = \frac{n(n-1)}{2}}$

$$* W_{22} = \{ A \in M_n(\mathbb{R}), \text{Trace}(A) = 0 \}$$

$0 \in W_{22}$, $\text{trace}(0) = 0$.

\Rightarrow let, $A \in W_{22}$, as $\text{trace}(A) = 0$

$B \in W_{22}$, as $\text{trace}(B) = 0$.

$$(\alpha A + \beta B) = C.$$

$$\text{Trace}(C) = \text{Trace}(\alpha A + \beta B)$$

$$= \alpha \text{Trace}(A) + \beta \text{Trace}(B)$$

$$= 0$$

$\Rightarrow W_{22}$ is subspace.

$$\Rightarrow \boxed{\dim(W_{22}) = n^2 - 1}$$

$W_{22} \neq \emptyset$,

$$W_{22} = \{ A \in M_n(\mathbb{R}), \text{trace}(A) = 0 \}$$

$$\Rightarrow \underline{\underline{\alpha}}, \underline{\underline{n=3}}$$

$$W_{22} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & (a_{11} - a_{22}) \end{bmatrix}$$

$$\Rightarrow \dim \text{of } W \text{ for } n=3 = \underline{\underline{8}}$$

$$\Rightarrow \boxed{\dim(W_{23}) = n^2 - 1}$$

* $W_{23} = \{ A \in M_n(\mathbb{R}) \mid \sum_{i=1}^n a_{ii} = 0, a_{11} = 0 \} \Rightarrow \boxed{\dim W_{23} = n^2 - 2}$

$\Rightarrow 0 \in W_{23} \neq \emptyset$. \downarrow
trace(A)=0.

$A \in W_{23} \Rightarrow \sum_{i=1}^n a_{ii} = 0, a_{11} = 0$

$B \in W_{23} \Rightarrow \sum_{i=1}^n b_{ii} = 0, b_{11} = 0$

$\alpha \cdot A + \beta B = C$

$\alpha (a_{ij}) + \beta (b_{ij}) = C_{ij}$

$$\sum_{i=1}^n C_{ii} = \alpha \sum_{i=1}^n a_{ii} + \beta \sum_{i=1}^n b_{ii}$$

$$= \alpha \cdot 0 + \beta \cdot 0$$

$$= 0$$

$C_{11} = \alpha a_{11} + \beta b_{11}$
 $= \alpha \cdot 0 + \beta \cdot 0$
 $C_{11} = 0$

$\Rightarrow \underline{W_{23}}$ is subspace.

$W_{23} = \{ A \in M_n(\mathbb{R}) \mid \text{trace}(A) = 0, a_{11} = 0 \}$

$n=3 \Rightarrow W = \{ A \in M_3(\mathbb{R}) \mid \text{trace}(A) = 0, a_{11} = 0 \}$

$$\left\{ \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \mid \text{trace}(A) = 0, a_{11} = 0 \right\}$$

$\Rightarrow = \begin{bmatrix} 0 & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & -a_{22} \end{bmatrix}$

$\Rightarrow \dim(W) = \underline{7}$

$\Rightarrow \boxed{\dim(W_{23}) = n^2 - 2}$

* $W_{25} = \{ A \in M_n(\mathbb{R}) \mid A = (a_{ij})_{n \times n}, \text{ with } a_{ij} = 0, \text{ where } i+j = \text{even} \}$

Here if we take $\{ A \in M_2(\mathbb{R}) \mid A = (a_{ij})_{2 \times 2}, \text{ with } a_{ij} = 0, \text{ where } i+j = \text{even} \}$

\underline{or}

$$\{ A = \begin{bmatrix} 0 & a_{12} \\ a_{21} & 0 \end{bmatrix}, \forall a_{ij} \in \mathbb{R} \}$$

Basis, $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}$

$\boxed{\dim = 2}$

$\Rightarrow W_{25}$ is subspace of $\mathbb{R}^{n \times n}$

$\dim W_{25} = \begin{cases} \frac{n^2}{2}, & n \text{ is even} \\ \frac{n^2-1}{2}, & n \text{ is odd} \end{cases}$

Note -

* $L_1 = \{ (x, 1), x \in \mathbb{R} \}$

$L_2 = \{ (x, 2), x \in \mathbb{R} \}$

$L_1 \cup L_2$ is not a subspace,

* two parallel lines about x-axis, may or may not be from a subspace.

* space of polynomials - $V = P_n(x)$ - (of degree at most 'n').

1) $W_{36} = \{ p \in V \text{ s.t. } p(0) = 0 \} = \{ p; p \text{ is a polynomial passing through origin} \}$

2) $W_{37} = \{ p \in V \text{ s.t. } p(2) = 0 \}$

3) $W_{38} = \{ p \in V \text{ s.t. } p(x) = p(1-x) \} \Rightarrow \dim W_{38} = \lfloor \frac{n}{2} \rfloor + 1$

4) $W_{39} = \{ p \in V \text{ s.t. } p(x) = p(x^2) \}$

5) $W_{40} = \{ p \in V \text{ s.t. } p(x) = [p(x)]^2 \}$

6) $W_{41} = \{ p \in V \text{ s.t. graph of } p(x) \text{ intersects } x\text{-axis at least two points} \}$

7) $W_{42} = \{ p \in V \text{ s.t. graph of } p(x) \text{ intersects } x\text{-axis at least two given points} \}$

8) $W_{43} = \{ p = a_0 + a_1x + \dots + a_9x^{10}, a_i \in \mathbb{R} \text{ with } a_1 + a_2 = 0, a_1 + a_3 = 0, a_1 - a_3 + a_4 = 0 \}$

9) $W_{44} = \{ p \in V \text{ s.t. } p(\alpha) = p(\beta) \}$

10) $W_{45} = \{ p \in V \text{ s.t. } p \text{ has local maxima} \}$

11) $W_{46} = \{ p = a_0 + a_1x + a_2x^2; a_i \in \mathbb{R}, p \text{ has extrema at } x=1 \}$

Solⁿ - $W_{36} = \{ p \in V; \text{ s.t. } p(0) = 0 \}$

$p, q \in W_{36} \Rightarrow p(0) = 0, q(0) = 0$

$\alpha p(x) + \beta q(x) = h(x)$

$h(0) = \alpha p(0) + \beta q(0)$

$= 0$

$\Rightarrow \alpha p(x) + \beta q(x) \in W$

$\Rightarrow W_{36}$ is subspace.

* $V = \{p; p(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n, a_i \in \mathbb{R}\}$
 $B = \{1, x, x^2, \dots, x^n\}$ is a basis of V .

* $W_{30} = \{p \in V, p(0) = 0\}$

or
 $W_{30} = \{p \in V, x(b_0 + b_1x + \dots + b_nx^n), b_i \in \mathbb{R}\}$

$B = \{x, x^2, x^3, \dots, x^n\}$

* $W_{30} = \{p \in V, p(\alpha) = 0\}$

or
 $W_{30} = \{p \in V, (x-\alpha)(b_0 + b_1x + \dots + b_nx^n), b_i \in \mathbb{R}\}$

$B = \{(x-\alpha), x(x-\alpha), \dots, x(x-\alpha)^{n-1}\}$

* $W_{49} = \{p \in V, p(1) = p(-1) = 0\}$

or
 $W_{49} = \{p \in V, (x-1)(x+1)(b_0 + b_1x + \dots + b_nx^{n-1}), b_i \in \mathbb{R}\}$

* $W_{38} = \{p \in V, \text{s.t. } p(x) = p(1-x)\}$

$\Rightarrow p, q \in W_{38}, p(x) = p(1-x)$
 $q(x) = q(1-x)$

$\alpha p(x) + \beta q(x) = h(x)$

replace x by $1-x$.

$\alpha p(1-x) + \beta q(1-x) = h(1-x)$

~~or~~ $\alpha p(x) + \beta q(x) = h(1-x)$

$h(x) = h(1-x)$

$\Rightarrow W_{38}$ is subspace

$$* W_{38} = \{ p \in V \text{ s.t. } p(x) = p(1-x) \}$$

$$p(x) = ax + b$$

$$p(1-x) = a(1-x) + b = ax + b \\ = a - ax + b = ax + b$$

$$2ax = a$$

$$a(2x-1) = 0$$

$$a=0$$

$p(x) = b$
(constant polynomial)

$$a \neq 0$$

$$x = \frac{1}{2}$$

$$p(x) = p(1-x)$$

only for $x = \frac{1}{2}$

for degree 1 polynomial.

If any polynomial of degree 1, s.t. $p(x) = p(1-x), \forall x$.

$$p(x) = ax^2 + bx + c$$

$$ax^2 + bx + c = a(1-x)^2 + b(1-x) + c$$

$$= a + ax^2 - 2ax + b - bx + c$$

$$2bx = a - 2ax + b$$

$$2bx - b = a - 2ax$$

$$b(2x-1) = a(1-2x)$$

$$b(2x-1) + a(2x-1) = 0$$

$$(2x-1)(a+b) = 0$$

$$a = -b$$

$$x = \frac{1}{2}$$

a general polynomial of degree 2 we have, $p(x) = p(1-x)$

$$p(x) = ax^2 + bx + c$$

$$= ax(x-1) + c$$

$$B = \{ 1, x(x-1) \}$$

$$W_{38}^I = \{ p, \text{ degree } p(x) \leq 2, p(x) = p(k-x) \}$$

$$= \left[\frac{n}{2} \right] + 1$$

$$B^I = \{ 1, x(n-1) \}$$

$$W_{38}^{II} = \{ p, \text{ degree } p(x) \leq 3, p(x) = p(k-x) \}$$

$$B^{II} = \{ 1, x(n-1) \}$$

$$W_{38}^{III} = \{ p, \text{ degree } p(x) \leq 4, p(x) = p(k-x) \}$$

$$B^{III} = \{ 1, x(n-1), x^2(n-1)^2 \}$$

$$* W_{39} = \{ p \in V, \text{ s.t. } p(x) = p(x^2) \}$$

$$\Rightarrow \alpha \cdot p(x^2) + \beta \cdot q(x^2) = h(x^2)$$

$$\alpha \cdot p(x) + \beta \cdot q(x) = h(x^2)$$

$$h(x) = h(x^2)$$

$$\alpha \cdot p(x) + \beta \cdot q(x) \in W$$

$$\Rightarrow \underline{W_{39} \text{ is subspace.}}$$

$\Rightarrow \nexists$ any polynomial of degree ≥ 1 which have the property

$$p(x) = p(x^2)$$

Hence, $W_{39} = \{ \}$ is subspace of constant polynomial.

$$B = \{ 1 \}$$

$$* W_{40} = \{ \}$$

* $W_{q1} = \{ p \in V, \text{ s.t. graph of } p(x) \text{ intersect } x\text{-axis at least two points} \}$

$p(x) = \hat{0}(x)$ (zero polynomial) $\in W_{q1}$

Let $(p(x)) \in W_{q1}$, $p(x)$ intersect x -axis at least two points

$h(x) = \alpha \cdot p(x) + \beta \cdot q(x) \in W_{q1}$,

$\alpha(p(x))$ also intersect x -axis at least two points.

$p(x) = x^2 - 1$

$q(x) = x^2 - 2$

$p(x) - q(x) = 1$.

$\Rightarrow W_{q1}$ is NOT subspace.

* $W_{q3} = \{ p = a_0 + a_1x + a_2x^2 + \dots + a_{10}x^{10}, a_i \in \mathbb{R}, \begin{matrix} a_1 + 2a_2 = 0, \\ a_2 + a_3 = 0, \\ a_1 - a_3 + a_4 = 0 \end{matrix} \}$

$\Rightarrow \dim W_{q3} = \dim W + 7 \leftarrow (\underbrace{a_0, a_5, a_6, a_7, a_8, a_9, a_{10}}_{7 \text{ choices}})$

$W = \{ p; p(x) = a_1x + a_2x^2 + a_3x^3 + a_4x^4 \}$

$a_1 + 2a_2 = 0$

$a_2 + a_3 = 0$

$a_1 - a_3 + a_4 = 0$

$\dim W = \dim$ of solution space of system $AX=0$.

where $A = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & -1 & 0 & 1 \end{bmatrix}_{3 \times 4}$, $X = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{pmatrix}$

$\dim W = n - r$

$= 4 - \text{rank}(A)$

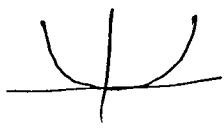
$= 4 - 3$

$\dim W = 1$

$\Rightarrow \dim W_{q3} = 8$

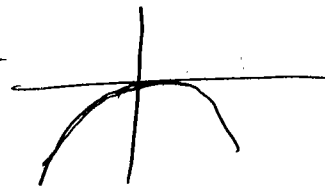
* $W_{45} = \{ p \in V, \text{ s.t. } 'p' \text{ has local maxima} \} \Rightarrow \text{Not subspace.}$

$$p(x) = x^2$$



$x=0$, local minima.

$$\langle \cdot, p(x) \rangle = -1 \cdot p(x) = -x^2$$



have no local minima.

* Space of sequences - over field \mathbb{R} .

① $W_{48} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is convergent} \}$

② $W_{49} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is divergent} \}$ ex. $\langle a_n \rangle = n, \langle b_n \rangle = -n$
 $\langle a_n + b_n \rangle = 0$ e.g. $\notin W_{49}$

③ $W_{50} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is monotonic} \}$

④ $W_{51} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ has at least one limit point} \}$

⑤ $W_{52} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is bounded} \}$ \Rightarrow sum of bdd is bdd.

⑥ $W_{53} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is unbounded} \}$ $\langle a_n \rangle = n$, unbd
 $\langle b_n \rangle = -n$, unbd

⑦ $W_{54} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ has infinitely many limit points} \}$

⑧ $W_{55} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is Cauchy} \}$ \Rightarrow sum of two Cauchy is Cauchy.

⑨ $W_{56} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ has unique limit point} \}$

⑩ $W_{57} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is oscillatory} \}$

⑪ $W_{58} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ has uncountable limit points} \}$ o.g. W_{59}

⑫ $W_{59} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ has countably infinite limit points} \}$ o.g. W_{60}

⑬ $W_{60} = \{ \langle a_n \rangle \in V, \text{ s.t. } \langle a_n \rangle \text{ is eventually monotonic} \}$

ex $W_{50} = \langle a_n \rangle = \{ 1, 1, 1, 1, 2, 2, 2, 2, \dots \}$

ex $W_{60} = \langle b_n \rangle = \{ -1, 1, -2, 2, \dots \}$

ex. $W_{51} = \langle a_n \rangle = \langle 1, 0, 2, 0, 3, 0, \dots \rangle$
 $W_{56} = \langle b_n \rangle = \langle 0, 1, 0, 2, \dots \rangle$ } one limit point.
 $\langle a_n + b_n \rangle = \langle 1, 1, 2, 2, \dots \rangle \Rightarrow$ no limit point

ex. $W_{53} = \langle a_n \rangle = n$ unbdd
 $\langle b_n \rangle = -n$ unbdd
 $\langle a_n + b_n \rangle = \langle 0 \rangle \notin W_{53} \Rightarrow$ not subspace

ex. $W_{54} = \langle 0 \rangle \notin W_{54} \Rightarrow$ not subspace

ex. $W_{57} = \langle a_n \rangle =$
 $\langle 0 \rangle \notin W_{57} \Rightarrow$ not subspace

ex. $W_{60} \Rightarrow \langle a_n \rangle = \langle 0, 1, 2, 1, 1, 1, 1, 2 \rangle$ } eventually monotonic
 $\langle b_n \rangle = \langle 0, 1, 2, -1, -1, 2, -2, -2, 2 \rangle$
 $\langle a_n + b_n \rangle = \langle 0, 2, 4, 0, 0, \dots \rangle$

$\Rightarrow \emptyset \in W_{60}$
 $\Rightarrow \text{d.t. } \notin W_{60}$

$W_{60} = \langle a_n \rangle = \langle 1, 5, 9, 10, 15, 20, \dots \rangle$ } eventually
 $\langle b_n \rangle = \langle 1, -6, -9, -9, -16, -19, \dots \rangle$ } monotonic

$\langle a_n + b_n \rangle = \langle 2, -1, 1, -1, 1, \dots \rangle \Rightarrow$ not eventually
 monotonic

$\Rightarrow W_{60}$ is not subspace.

* space of functions -

$V =$ space of functions defined on I :

$\checkmark W_{62} = \{ f \in V \text{ s.t. } f \text{ is bdd fun on } I \}$

$\times W_{63} = \{ f \in V \text{ s.t. } f \text{ is monotone on } I \}$ $[x] = x - [x]$

$\times W_{64} = \{ f \in V \text{ s.t. } f \text{ is periodic on } I \}$ = Linear combination
P, F may or may not be periodic

$\checkmark W_{65} = \{ f \in V \text{ s.t. } f \text{ is cts on } I \}$

$\times W_{66} = \{ f \in V \text{ s.t. } f \text{ is disc on } I \}$, zero fun $\notin W_{66}$

$\checkmark W_{67} = \{ f \in V \text{ s.t. } f \text{ is Lipschitz on } I \}$ - sum of Lipschitz is Lipsch

$\checkmark W_{68} = \{ f \in V \text{ s.t. } f \text{ is Riemann integrable on } I = [a, b] \}$

$\checkmark W_{69} = \{ f \in V \text{ s.t. } f \text{ is of Bounded variation on } I = [a, b] \}$

$\checkmark W_{70} = \{ f \in V \text{ s.t. } f \text{ is U.C. on } I \}$

$\checkmark W_{71} = \{ f \in V \text{ s.t. } f \text{ is diff. on } I \}$

$\times W_{72} = \{ f \in V \text{ s.t. } f \text{ is convex on } I \}$

$\times W_{73} = \{ f \in V \text{ s.t. } f \text{ is concave on } I \}$

$\checkmark W_{74} = \{ f \in V \text{ s.t. } f \text{ satisfy the Rolle's thm on } [a, b] \}$

$\checkmark W_{75} = \{ f \in V \text{ s.t. } f \text{ satisfy the Lagrange's mean value thm on } [a, b] \}$

~~$W_{76} = \{ f \in V \text{ s.t. } \int_a^b f(x) dx = 0, \forall n \in [a, b] \}$~~

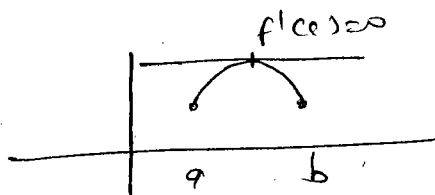
$\checkmark W_{77} = \{ f \in V \text{ s.t. } f \text{ is cts s.t. } \int_0^1 [f(x)]^2 dx = 0 \}$ This is only
= zero space

$\Rightarrow W_{74} =$

Rolle's th^m

Let, $f: [a, b] \xrightarrow{cs} \mathbb{R}$ not const in the graph
 $f: (a, b) \xrightarrow{\text{diff}} \mathbb{R}$ & $a, c \in (a, b)$ have unique
s.t. $f(a) = f(b)$.

$\exists c \in (a, b)$ s.t. $f'(c) = 0$.



$$0 \in W_{74}$$

$$\Rightarrow W_{74} \neq \emptyset$$

$$f(x), g(x) \in W_{74}$$

f, g const on $[a, b] \Rightarrow f+g$ is const on $[a, b]$

f, g diff on $(a, b) \Rightarrow f+g$ diff on (a, b)

$$f(a) = f(b), g(a) = g(b)$$

$$f(a) + g(a) = f(b) + g(b)$$

$$(f+g)(a) = (f+g)(b)$$

$\exists c \in (a, b)$ s.t. $f'(c) = 0$,

$\Rightarrow W_{74}$ is subspace.

$\Rightarrow W_{76} =$

$$f, g \in W_{76}$$

$$\int_a^b f(x) dx = 0, \int_a^b g(x) dx = 0,$$

$$\alpha \cdot f + \beta \cdot g = h(x)$$

$$\int_a^b h(x) dx = \int_a^b [\alpha f(x) + \beta g(x)] dx$$

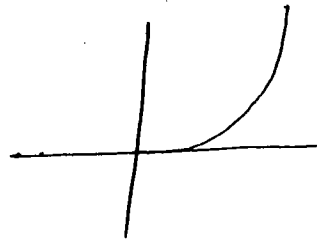
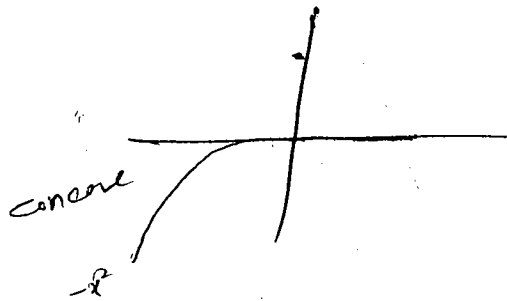
$$= 0.$$

$\Rightarrow W_{76}$ is subspace.

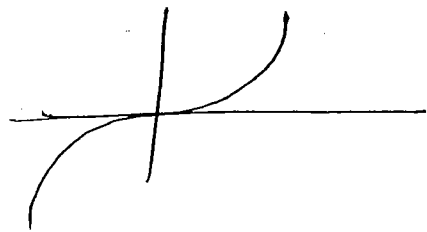
78. $W_{78} = \{ f \in V \text{ s.t. } f \text{ is either convex or concave on } \mathbb{R} \}$

$$g(x) = \begin{cases} -x^2, & x \geq 0 \\ 0, & x \leq 0 \end{cases}$$

$$f(x) = \begin{cases} 0, & x \leq 0 \\ x^2, & x > 0 \end{cases}$$



$$f(x) + g(x) = \begin{cases} x^2, & x \geq 0 \\ -x^2, & x \leq 0 \end{cases}$$



Neither, convex nor concave.
 $\Rightarrow W_{78}$ is not subspace

$W_{79} = \{ f \text{ is complex valued function s.t. } f \text{ is analytic fun}^n \}$

$W_{80} = \{ f \text{ is complex valued function s.t. } f \text{ is satisfy C.R eq}^n \}$

* Linear combination -

Let, 'V' is a vector space over field 'F',
and let, x_1, x_2, \dots, x_n are n-vectors of vector space
'V' and let, a vector $x \in V$ and the scalars,
 $\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_n \in F$ s.t.

$$x = \alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_n x_n$$

Then, 'x' is called a Linear combination of ^{the} vectors x_i 's
by using the scalars α_i 's. & they are always unique.

* Note ① - Linear combination can be discussed over FVVS
or over Non-FVVS.

② - set of vectors x_i 's should be finite.

* Linear span / Generating set / spanning set -

Let, $S = \{x_1, x_2, x_3, \dots, x_n\}$ be the set of vectors
of $V(F)$ then the linear span of 'S' is denoted by $L(S)$
and defined as,

$L(S)$ is the intersection of all the subspaces
containing 'S'.

(Hence, $L(\emptyset) = \{0\}$, as $L(\emptyset) = \cap$ of all the subspaces
containing \emptyset .
 $= \{0\} \cap W_1 \cap W_2 \cap \dots$
 $= \{0\}$

$$\Rightarrow \boxed{L(\emptyset) = \{0\}}$$

$$\text{also, } \boxed{L\{0\} = \{0\}}$$

Hence, $L(S)$ is the smallest subspace of V which contains 'S'.

If 'S' is Nonempty, then $L(S)$ is the collection of all
possible linear combinations.

$$\# S = \{x_1, x_2, x_3, \dots, x_n\} \subseteq V.$$

$$|F| = p^r$$

Let, $x \in L(S)$ (arbitrary vector of $L(S)$)

$$\Rightarrow \exists \alpha_1, \alpha_2, \dots, \alpha_n \in F \text{ s.t.}$$

$$x = \alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_n x_n$$

$$\begin{array}{ccc} \downarrow & \downarrow & \downarrow \\ p^r & p^r & p^r \\ \text{choices} & \text{choices} & \text{choices} \end{array}$$

$$\begin{aligned} \text{total choices for } x &= p^r \cdot p^r \cdot \dots \cdot p^r \text{ (n-times)} \\ &= p^{n \cdot r} \end{aligned}$$

$$\text{Hence, } |L(S)| \leq p^{n \cdot r}$$

$$\boxed{|L(S)| \leq |F|^{|S|}}$$

$\#$ Let, $S = \{x_1, x_2, x_3, \dots, x_n\}$ is L.D.

WLOG, $x_2 (1 \leq i \leq n)$ is L.C. of preceding vectors.

$$x_2 \in L\{x_1, x_2, \dots, x_{i-1}, x_{i+1}, \dots, x_n\}$$

$$\text{Here, } L(S) = L\{x_1, x_2, \dots, x_{i-1}, x_{i+1}, x_n\}$$

$$|L(S)| \leq p^{r(n-1)} < p^{n \cdot r}$$

Hence, if 'S' is L.D., $|S| = n$, with $|F| = p^r$.

$$\text{Then, } \boxed{|L(S)| < p^{n \cdot r}}$$

MODERN * ALGEBRA

Monu Kummar

Page No.

Date: / /

Set: Collection of well-defined distinct objects is called set.

Cartesian Product :- Let A, B be two sets.

$$A \times B = \{(a, b) : a \in A, b \in B\}$$

is called cartesian product of A & B .

e.g. let $A = \{1, 2, 3\}$, $B = \{1, 2\}$

$$\Rightarrow A \times B = \{(1, 1), (1, 2), (2, 1), (2, 2), (3, 1), (3, 2)\}$$

Note: If $|A| = m$, $|B| = n$ then $|A \times B| = m \cdot n$.

Relation :- A relation from A to B is a subset of $A \times B$. Infact, every subset of $A \times B$ is a relation from A to B .

$$\Rightarrow \text{No. of relations from } A \text{ to } B = \text{No. of subsets of } A \times B = 2^{|A \times B|}$$

Note: A relation from A to A is a subset of $A \times A$

$$\Rightarrow \text{No. of relations on } A = \text{No. of subsets of } A \times A = 2^{|A \times A|}$$

Type of Relation :-

(1) **Identity Relation** - Let $I \subseteq A$, such that if $a \in A$ then $(a, a) \in I$ (only).

i.e. if $a \in A \Rightarrow a R a$ only.

Ques: let $A = \{1, 2, 3\}$

$$\Rightarrow A \times A = \{(1, 1), (1, 2), (1, 3), (2, 1), (2, 2), (2, 3), (3, 1), (3, 2), (3, 3)\}$$

\times $S = \{(1, 1), (2, 2)\}$ is identity relation? Then -

- ✓ ii) $S = \{(1,1), (2,2), (3,3)\}$ is identity relation
 ✗ iii) $S = \{(1,1), (2,2), (3,3), (1,3)\}$ is identity relation
 ✗ iv) $S = \phi$ is identity relation

Note: If $A = \phi \Rightarrow A \times A = \phi \times \phi$ & $S = \phi \subseteq \phi \times \phi$
 then S is an identity relation.

[2] **Reflexive Relation** - Let $S \subseteq A \times A$ s.t. if $a \in A$
 then $(a,a) \in S$.

i.e. if $a \in A$ then aRa then S is called reflexive relation.

Ques - Let $A = \{1, 2, 3\}$

$\Rightarrow A \times A = \{(1,1), (1,2), \dots, (3,3)\}$ Then -

- ✗ i) $S = \{(1,1), (2,2)\}$ is reflexive
 ✓ ii) $S = \{(1,1), (2,2), (3,3)\}$ is reflexive
 ✗ iii) $S = \{(1,1), (2,2), (3,3), (1,3)\}$ is reflexive
 ✗ iv) $S = \phi$ is reflexive

Note: - If S is a reflexive relation on a set A &
 I is identity relation then $I \subseteq S$.

[3] **Irreflexive relation** - Let $S \subseteq A \times A$ s.t. if $a \in A$
 then $(a,a) \notin S$.

i.e. if $a \in A$ then $a \not R a$ then S is called Irreflexive relation.

Ques: Let $A = \{1, 2, 3\}$

$\Rightarrow A \times A = \{(1,1), (1,2), \dots, (3,3)\}$ then

- ✗ i) $S = \{(1,1), (1,2)\}$ is irreflexive relation

Mohu Kumar

- ✓ ii) $S = \{(1,2), (2,1)\}$ is irreflexive relation
 ✓ iii) $S = \{(1,2), (1,3), (2,3)\}$ is irreflexive relation
 ✗ iv) $S = \{(1,1), (1,3)\}$ is irreflexive relation
 ✓ v) ϕ is irreflexive relation

Note - IF S is Irreflexive relation then - $S \cap I = \phi$.

4] Symmetric Relation - Let $S \subseteq A \times A$ s.t. if $(a,b) \in S$ then $(b,a) \in S$.

i.e. if aRb then bRa

then S is called symmetric relation.

Ques - Let $A = \{1,2,3\}$

$\Rightarrow A \times A = \{(1,1), (1,2), (1,3), (2,1), \dots, (3,3)\}$ Then -

- ✓ i) $S = \{(1,1)\}$ is symmetric relation
 ✓ ii) $S = \{(1,1), (2,2), (3,3)\}$ is symmetric relation
 ✓ iii) $S = \{(1,2), (2,1)\}$ is symmetric relation
 ✗ iv) $S = \{(1,3)\}$ is symmetric relation
 ✓ v) $S = \phi$ is symmetric relation

5] Asymmetric Relation - Let $S \subseteq A \times A$ if $(a,b) \in S$
 $\Rightarrow (b,a) \notin S$ then S is

called asymmetric relation.

if $a = b \Rightarrow (a,a) \notin S$.

Ques - Let $A = \{1,2,3\}$

$\Rightarrow A \times A = \{(1,1), (1,2), \dots, (3,3)\}$ Then which of the following is ~~is~~

- ✗ i) $S = \{(1,1)\}$ ✓ iv) $S = \{(1,3), (1,2), (2,3)\}$
 ✓ ii) $S = \{(2,3)\}$ ✓ v) $S = \phi$
 ✗ iii) $S = \{(1,2), (2,1)\}$

[6] **Anti-symmetric Relation** :- Let $S \subseteq A \times A$ such that
if $(a, b), (b, a) \in S \Rightarrow a = b$

then S is called anti-symmetric relation.

i.e. if $a R b$ & $b R a \Rightarrow a = b$

if $a = b \Rightarrow (a, a) \in S$.

Ques: Let $A = \{1, 2, 3\}$

$\Rightarrow A \times A = \{(1, 1), (1, 2), \dots, (3, 3)\}$. Then -

✓ i) $S = \{(1, 1), (2, 2)\}$ is antisymmetric relation

✓ ii) $S = \{(1, 1), (2, 2), (3, 3), (1, 3)\}$ is antisymmetric relation

✓ iii) $S = \{(1, 1), (1, 2)\}$ is antisymmetric relation

✓ iv) $S = \phi$ is antisymmetric relation

X v) $S = \{(1, 1), (2, 2), (3, 3), (1, 2), (2,)\}$ is antisymmetric relation

[7] **Transitive Relation** :- Let $S \subseteq A \times A$ such that -

if (a, b) & $(b, c) \in S \Rightarrow (a, c) \in S$.

i.e. if $a R b$ & $b R c \Rightarrow a R c$

then S is called transitive relation.

Ques: Let $A = \{1, 2, 3\}$

$\Rightarrow A \times A = \{(1, 1), (1, 2), \dots, (3, 3)\}$ Then -

✓ i. $S = \{(1, 2), (2, 3), (1, 3)\}$ is transitive relation

✓ ii. $S = \{(1, 1), (2, 2), (3, 3)\}$ is transitive relation

✓ iii. $S = \{(1, 2)\}$ is transitive relation

✓ iv. $S = \phi$ is transitive relation

Equivalence Relation :- Let $S \subseteq A \times A$ such that -

S is - i) Reflexive ii) symmetric &

iii) Transitive

then S is called equivalence relation.

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Ques:- Let $A = \{1, 2, 3\}$

$\Rightarrow A \times A = \{(1,1), (1,2), \dots, (3,3)\}$ Then -

✓ i) $S = \{(1,1), (2,2), (3,3)\}$ is equivalence relation

x ii) $S = \{(1,1), (2,2)\}$ is equivalence relation

x iii) $S = \phi$ is equivalence relation

✓ iv) $S = \{(1,1), (2,2), (3,3), (1,3), (3,1)\}$ is equi. relation

Ques- Let $A =$ collection of all straight line in plane. define a relation R on A such that -

if $L_1, L_2 \in A$ then $L_1 R L_2$ iff $L_1 \parallel L_2$.

Then R is an equi. relation on A ?

Ques:- Let $A =$ collection of all straight line in plane.

define a relation R on A s.t. if $L_1, L_2 \in A$

then $L_1 R L_2$ if $L_1 \perp L_2$.

Then R is not an equi. relation on A ?

Ques:- Define a relation R on A (collectⁿ of all human being s.t. $a, b \in A$, $a R b$ iff a is brother b

Then R is not an equivalence relation?

Ques:- $A =$ collectⁿ of all mens.

define a relation R on A s.t. $a, b \in A$,

$a R b$ iff a is brother b

Then R is an equivalence relation?

Counting of Relation \Rightarrow

Let $A = \{a_1, a_2, \dots, a_n\}$

$\Rightarrow A \times A = \{(a_1, a_1), (a_1, a_2), \dots, (a_n, a_n)\}$

i) Identity relation - if $a \in A \Rightarrow (a, a) \in S$ only.

Now :-

$$\begin{array}{ll}
 (a_1, a_1) - 1 \text{ (choice)} & (a_1, a_2) - 1 \text{ (choice)} \\
 (a_2, a_2) - 1 & \vdots \\
 \vdots & \vdots \\
 (a_n, a_n) - 1 \text{ (choice)} & (a_i, a_j) - 1 \text{ if } i \neq j
 \end{array}$$

\Rightarrow No. of identity relations = $1 \cdot 1 \cdot 1 \dots = 1$
 n^2 times.

[2] Reflexive - $S \subseteq A \times A$, if $a \in A \Rightarrow (a, a) \in S$ (Reflexive)

$$\begin{array}{ll}
 (a_1, a_1) - 1 \text{ (choice)} & (a_1, a_2) - 2 \text{ (choices)} \\
 (a_2, a_2) - 1 \text{ (choice)} & (a_2, a_1) - 2 \text{ (choices)} \\
 \vdots & \vdots \\
 (a_n, a_n) - 1 \text{ (choice)} & (a_i, a_j) - 2 \text{ if } i \neq j
 \end{array}$$

\Rightarrow No. of reflexive relations = $(1 \cdot 1 \cdot 1 \dots 1) (2 \cdot 2 \cdot 2 \dots 2)$
 n -times n^2-n times
 $= 2^{n^2-n}$

[3] Irreflexive - $S \subseteq A \times A$, if $a \in A \Rightarrow (a, a) \notin S$. (Irreflexive)

$$\begin{array}{ll}
 (a_1, a_1) - 1 \text{ (choice)} & (a_1, a_2) - 2 \text{ (choices)} \\
 (a_2, a_2) - 1 \text{ (choice)} & (a_2, a_1) - 2 \text{ (choices)} \\
 \vdots & \vdots \\
 (a_n, a_n) - 1 \text{ (choice)} & (a_i, a_j) - 2 \text{ if } i \neq j
 \end{array}$$

\Rightarrow No. of Irreflexive relations = $(1 \cdot 1 \dots 1) (2 \cdot 2 \dots 2)$
 n^2-n times
 $= 2^{n^2-n}$

[4] Symmetric - if $(a, b) \in S \Rightarrow (b, a) \in S$ (Symmetric)
 if $a = b$, $(a, a) \in S$.

15/5/17

Vinit Raj

①

Partial Differential Equations

(4-5 questions)

(15 to 20 marks)

Syllabus:-

- also imp [1] Origin of Pde.
 [2] Classification of linear and non-linear pde.
 100% imp [3] First order and first degree pde and Solution by Lagrange's method. (1) ans
 (Extension of Lagrange's method).

- 100% imp [4] Non-linear Partial diff. eqn [1st order but not of first degree]. (1) ans
 [5] Classification of second order Pde and their canonical forms:
 → Parabola
 → hyperbola
 → ellipse

- also imp [6] Product method (separation method).
 [7] Heat equation
 [8] Wave equation
 [9] Laplace equation. (1-2) ans
 [10] Dirichlet eqn. } Boundary
 [11] Neumann eqn. } or interior of circles.
 [12] Characteristic of non-linear Pde.

॥ यशस्वता की कुंजी है ॥
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* Partial diffⁿ eqⁿ :- P.D.E is partial diffⁿ eqⁿ is a relation between dependent variable and some of its derivatives w.r to more than one independent variables.

$$\frac{\partial z}{\partial x} + \frac{\partial z}{\partial y} + z = 0$$

→ dependent
← independent

$$\frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial x \partial y} = \sin(x+y)$$

not in discussion at

$$\frac{\partial^2 z}{\partial x_1^2} + \frac{\partial z}{\partial x_1} + \frac{\partial^2 z}{\partial x_2^2} + \frac{\partial z}{\partial x_2} + \frac{\partial^2 z}{\partial x_3^2} + \frac{\partial z}{\partial x_3} = x_1 + x_2 + x_3$$

z - dependent
 $x_1, x_2, x_3 \rightarrow$ independent

* Order of P.D.E :-

The order of highest derivative occurring in p.d.e is called the order of PDE.

eg: - i) $\frac{\partial^2 z}{\partial x^2} + \frac{\partial z}{\partial x \partial y} = \sin(x+y)$

highest derivatives is two
 \Rightarrow order is 2.

ii) $\frac{\partial z}{\partial y} + \frac{\partial z}{\partial x} + z = \sin z$

\Rightarrow order is 1 but degree not defined

iii) $\frac{\partial^2 y}{\partial x^2} + \frac{dy}{dx} + y = \sin y$ → independent var

$$= \frac{1-y^3}{3!}$$

\Rightarrow order is 2
 but degree is not defined.

* Degree of P.D.E :-

(2)

The power of highest derivative in p.d.e after made it free from radicals and fractions, so far as derivative are concerned.

eg:- $\frac{dy}{dx} = \sqrt{\sin x}$ → power is radical

⇒ $\left(\frac{dy}{dx}\right)^2 = \sin x$ → order is 1, degree is 2 (free from radicals)

Example:- $\left(\frac{dy}{dx}\right) = \left(\frac{2\left(\frac{dy}{dx}\right)^2 + y}{\frac{dy}{dx}}\right)$

⇒ $\left(\frac{dy}{dx}\right)^2 = 2\left(\frac{dy}{dx}\right)^2 + y$ (free from fraction)

⇒ $\left(\frac{dy}{dx}\right)^2 + y = 0$ → order is 1, degree is 2.

eg $\sin\left(\frac{dy}{dx}\right) + y = 2$ can't be free from radicals.

⇒ order is 1, but degree not defined.

Note:- If there is any radicals or fractions in p.d.e the order is not change.

Note:- If dependent variable or its derivative containing in p.d.e in such a way that they can't free from the radicals. (eg:- $\sin\left(\frac{dy}{dx}\right)$, $e^{\left(\frac{dy}{dx}\right)}$) degree is not defined.

Note:- $\frac{\partial z}{\partial x} = p$, $\frac{\partial z}{\partial y} = q$, $\frac{\partial^2 z}{\partial x^2} = r$, $\frac{\partial^2 z}{\partial x \partial y} = s$, $\frac{\partial^2 z}{\partial y^2} = t$.

z = dependent, x, y → independent.

* Linear and non-linear pde :-

A pde is said to be linear if the dependent var. and its derivative occurs ^{only} in the first degree and are not multiplied.

And if it is not linear then is called non-linear.

- Example :- $\frac{\partial z}{\partial x} + \frac{\partial z}{\partial y} + z = x \rightarrow$ linear.

2) $z \cdot \frac{\partial z}{\partial x} + x \cdot \frac{\partial z}{\partial y} = 0 \rightarrow$ not linear
 two dependent z
 & $\frac{\partial z}{\partial x}$ is multiply

3) $\left(\frac{\partial z}{\partial x}\right)^2 + \frac{\partial z}{\partial y} = 2 \rightarrow$ not linear
 \rightarrow first order but not first degree.
 \rightarrow non-linear.
 derivative multiply

* Classification of first order p.d.e :-

1) Linear p.d.e :- A p.d.e $F(x, y, z, p, q) = 0$ is said to be linear p.d.e of order 1 if it is linear in p, q and z.

And equation can be written in the form

$$P(x, y) \cdot p + Q(x, y) \cdot q + R(x, y) \cdot z = F(x, y)$$

where $P(x, y), Q(x, y), R(x, y)$ are fⁿ of x and y only.

Example :- 1) $x^2 p + y^2 q = 0$

2) $e^{x+y} \cdot p + \sin(y-x) \cdot q = x^2 + y^2 \}$ linear

3) $x^2 p - y^2 q = z^2 + xy \rightarrow$ not linear
 not linear in z \rightarrow R is not uniform in y

2) Semi linear :-

A pde eqⁿ $F(x, y, z, p, q) = 0$ is said to be Semi linear if it is linear in p and q and can be written in the form

$$P(x, y) \cdot p + Q(x, y) \cdot q + R(x, y, z) = F(x, y)$$

(or)

$$P(x, y) p + Q(x, y) q = R(x, y, z)$$

Example :- $x^2 p + y^2 q + z^2 = (x+y)$

(or) $\downarrow \quad \downarrow$
 $R(x, y, z) \quad F(x, y)$

$$x^2 p + y^2 q = \underbrace{(x+y) - z^2}_{R(x, y, z)}$$

Example :- $p + q + z = 0 \rightarrow$ (linear, semi linear)

$p + q + z^2 = 0 \rightarrow$ (semi linear, not linear)
 \downarrow z^2 is not linear

Note :- Linear Pde \Rightarrow semi linear Pde
 but semi linear $\not\Rightarrow$ linear Pde

3) Quasi linear pde :-

A pde $F(x, y, z, p, q) = 0$ is said to be quasi linear pde if it can be written as

$$P(x, y, z) \cdot p + Q(x, y, z) \cdot q = R(x, y, z)$$

Example :- $x^2 z p + y^2 q = z^2(x+y)$

Note :- Linear \Rightarrow Semi linear \Rightarrow Quasi linear.

16/5/17

Q1) The diffⁿ eqn is $y \cdot \frac{\partial u}{\partial x} + u \cdot \frac{\partial u}{\partial y} = 5u \cdot x$ ($x, y > 0$)

- i) linear homogeneous.
- ii) linear non homogeneous.
- iii) ~~Quasi linear.~~
- iv) Semi linear.

Q2) The given PDE is $(x^2 + y^2) z_x + x^3 z_y = xy z^2$
($\because z_x = \frac{\partial z}{\partial x}$
 $z_y = \frac{\partial z}{\partial y}$)

- i) Linear.
- ii) Semi but not quasi.
- iii) ~~Semi but not linear.~~
- iv) non-linear.

Solⁿ 1) $y \cdot u_x + u \cdot u_y = 5u \cdot x$
 $y \cdot p + u \cdot q = 5u \cdot x$

here is multiplication of $u \cdot \frac{\partial u}{\partial y}$ \Rightarrow not linear
 \Rightarrow not semi linear
as variable and dependent variables
of its derivative

Solⁿ 2) $(x^2 + y^2) \cdot p + x^3 \cdot q = xy(z^2) \rightarrow z$ is not linear

\Rightarrow semi linear
 \Rightarrow Quasi linear

+ SETS AND FUNCTIONS +

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Sets :- The collection of well-defined objects, is called set. collection should be of distinct objects.

That is, we can say collection of all such type of elements or objects which satisfy some rule, it is possible to say, whether a particular objects belongs to the collection or not. ①

e.g. $S = \{ \text{collection of elements from } \mathbb{Z} \text{ which satisfy } 2x^3 + x^2 - 2x - 1 = 0 \}$

i.e. $S = \{ x \in \mathbb{Z} \text{ s.t. } 2x^3 + x^2 - 2x - 1 = 0 \}$

as we put $x = 1, -1, -\frac{1}{2}$ in $2x^3 + x^2 - 2x - 1$ we get 0; but out of these only 1 and -1 belongs to \mathbb{Z} . 1 and -1 are only two objects which satisfy the given rule.

The given rule is that, x should be from \mathbb{Z} and satisfies $2x^3 + x^2 - 2x - 1 = 0$.

Hence S is nothing only $S = \{ 1, -1 \}$

e.g. $T = \{ x \in \mathbb{R} \text{ s.t. } x \neq x \}$

As we know, every element or every real number is always equal to itself. So there is no real number which satisfies the given rule. Hence T is empty

i.e. $T = \emptyset$

Equality of Sets :- Two sets are said to be equal when they consists of exactly the same elements.

Subset :- If S and T are two sets s.t. each member of S is also member of T . Then S is subset of T and denoted as $S \subseteq T$.

i.e. $x \in S \Rightarrow x \in T$

\Rightarrow $S \subseteq T$

Vinit Raj Chauhan

Note :- If $x \in A \Rightarrow x \in B$ and if there is $y \in B$ but $y \notin A$, then A is called proper subset of B . written as $A \subset B$

Note :- Every set is subset of itself.

Note :- Empty set is a subset of every set.

Note :- Empty set is unique.

Russel paradox :- There is no set of all sets

Let $A = \{ x \text{ is a set, } x \notin x \}$

Let if possible A is a set

$\Rightarrow A \in A$; but if any element belongs to

A say x satisfies $x \notin x$, so here. if $A \in A$ if $A \notin A$ [contradiction],

contradiction coming by taking wrong assumption
Hence, There is no set of all sets

Paradox means self contradictory statement

Cardinality of a Set :-

The number of elements in any set A is called cardinality of A. It is denoted by Card(A) or |A| ..

e.g. $S = \{ e, i, o, a, u \}$.

$Card(S) = |S| = 5$

Power Set :-

The set of all subsets of any set S is said to be a power set, and it is denoted by P(S) (2)

e.g. $S = \{ p, q, r \}$, then

$P(S) = \{ \phi, S, \{p\}, \{q\}, \{r\}, \{p, q\}, \{p, r\}, \{q, r\} \}$

here $|P(S)| = Card P(S) = 8 = 2^3$

Note :-

If set S contains n elements then its power set will contain 2^n elements i.e. cardinality of power set is 2^n ($|P(S)| = 2^n$)

Proof

$Card(P(S)) =$ Number of sets with no elements
 +
 Number of subsets with 1 elements
 +
 Number of subsets with 2 elements
 +
 |
 Number of subsets with n elements

i.e. $|P(S)| = nC_0 + nC_1 + nC_2 + \dots + nC_n$
 $= 1 + nC_1 + nC_2 + \dots + 1$
 $= (1+1)^n$

$|P(S)| = 2^n$

Cartesian Product of sets :- for any two sets A and B , cartesian product of A and B is denoted by $A \times B$ and defined as -

$$A \times B = \{(a, b); a \in A, b \in B\}$$

For three sets A, B and C ,

$$A \times B \times C = \{(a, b, c), a \in A, b \in B, c \in C\}$$

In General

$$\prod_{i=1}^n A_i = A_1 \times A_2 \times A_3 \times \dots \times A_n = \{(a_1, a_2, \dots, a_n), a_i \in A_i, \forall i=1 \text{ to } n\}$$

here (a_1, a_2, \dots, a_n) called an ordered n -tuple.

Results :-

(1) If $|A| = m$ & $|B| = n$ then $|B \times A| = |A \times B| = m \times n = m \cdot n$

(2) $A \times B \iff B \times A$ iff $A = B$

(3) If $|A \cap B| = m$ then $|(A \times B) \cap (B \times A)| = m^2$

(4) $A \subset B \implies A \times C \subset B \times C$

(5) $A \times (B \cup C) = (A \times B) \cup (A \times C)$

(6) $A \times (B \cap C) = (A \times B) \cap (A \times C)$

(7) $(A \times B) \cap (C \times D) = (A \cap C) \times (B \cap D)$

(8) $(A \times C) - B \times C = (A - B) \times C$

(9) $A \subset B$ and $C \subset D$ then $A \times C \subset B \times D$

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Union and Intersection of sets :

$$A \cup B = \{x; x \in A \text{ or } x \in B\}$$

$$A \cap B = \{x; x \in A \text{ and } x \in B\}$$

Properties, for any sets A, B and C .

(1) $A \subset A \cup B$

(2) $B \subset A \cup B$

(3) $A \cup A = A$ (Idempotent law)

(4) $A \cup (B \cup C) = (A \cup B) \cup C$ (Associative law)

(5) $A \cap B \subset A$

(6) $A \cap B \subset B$

(7) $A \cap \phi = \phi$

(8) $A \cap A = A$ (Intersection is Idempotent)

③

(9) $A \cap (B \cap C) = (A \cap B) \cap C$ (Associative)

Disjoint Set: Two sets A and B are said to be disjoint if they have no element in common, means their intersection should be ϕ .

i.e. A and B are disjoint if $A \cap B = \phi$

Note Every disjoint sets are distinct sets, not conversely.

e.g. $S = \{1, 2, 3, 4\}$, $T = \{2, 5, 7, 8\}$.

here S and T are distinct but not disjoint because $S \cap T = \{2\} \neq \phi$.

Difference of two sets :-

$$A - B = \{x, x \in A \text{ and } x \notin B\}$$

All elements which are in A but not in B .

Note (1) Difference not commutative (i.e. $A - B \neq B - A$)

Note (2) Difference not associative (i.e. $A - (B - C) \neq (A - B) - C$)

Symmetric Difference :- Let X and Y are two sets then symmetric difference of sets X and Y denoted by $X \Delta Y$ and defined as

$$X \Delta Y = (X - Y) \cup (Y - X) = (X \cup Y) - (X \cap Y)$$

Functions Or Mappings :- Let A and B are two sets; if there is a rule ' f ' which assigns to every element of A to a unique element of B . Then such a rule ' f ' is called a function from Set A to B .

We write it as $f: A \longrightarrow B$. Here A is called domain and B is called co-domain of function f .

Note: If we take two different domain for same rule f , then can be consider as two distinct function.

i.e. Let $f: A \longrightarrow B$ s.t. $f(x) = \sin x$
& $f: C \longrightarrow B$ s.t. $f(x) = \sin x$.

here rule for both are same $f(x) = \sin x$ but domain are different, that's why $f: A \longrightarrow B$ and $f: C \longrightarrow B$ can consider as two distinct function.

Note Two functions ' f ' and ' g ' are equal iff.

(I) domain of ' f ' = domain of g

(II) $f(x) = g(x) \quad \forall x \in \text{domain}$.